# **Excel for Crash Reconstruction**

#### **2021 Annual Conference**

09/28/21 – 10/01/21 Crown Plaza Conference Center Springfield, IL







# **Topics**

**Case Applications** 

**Excel Interface** 

Formula Basics

**Excel Crash Recon Basics** 

Formatting

**Conditional Formatting** 

Printing

Copying

**Advanced Formulas** 





**Excel for Crash Reconstruction** 

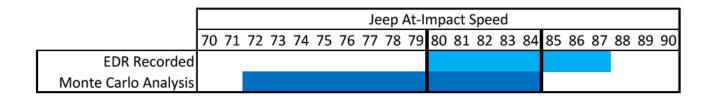




# Report your test results

Run Number	29	30	31	33	34
Speed (mph)	42.2	41.7	43.9	43.4	43.9
Distance (ft)	74.0	71.5	76.2	78.0	80.2
Coefficient of Friction	0.823	0.813	0.873	0.828	0.823
Considered Values	0.823	0.813	-	0.828	0.823
<b>Average Coefficient of</b>			0.822		
Friction - μ	U.022				

# Report and graph your findings





# **Complete basic calculations**

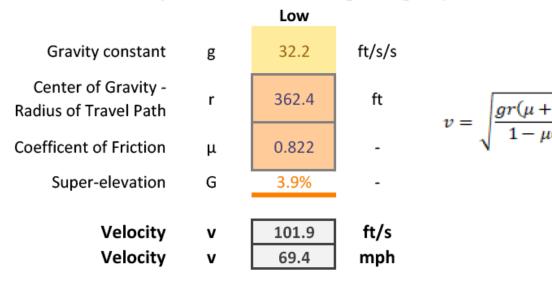
#### Super-elevation at yaw

Change in Height Change in Distance Super-elevation h d G 0.471 12.12 3.9%

ft ft

$$G = \frac{\Delta h}{\Delta d}$$

#### Velocity of Mitsubishi at beginning of yaw





# **Duplicate difficult calculations**

Max force per inch of damage width with no permanent damage:

Linear spring stiffness per inch of damage width:

Vehicle weight: Damage width:

Angle of applied force:

Damage measurements:

Damage measurements: Damage measurements:

Damage measurements: Damage measurements:

Damage measurements:

	Mercedes	BMW	Dodge	Averag
A=	573.9	440.4	757.2	590.5
B=	281.9	209.3	411.5	300.9
w=	5370	5370	5370	5370
W=	72.4	72.4	72.4	72.4
θ=	40	40	40	40
C1=	2.7	2.7	2.7	2.7
C2=	25.4	25.4	25.4	25.4

C2 in C3= 25.5 25.5 25.5 25.5 in C4= 22.5 22.5 22.5 22.5 in C5= 12.8 12.8 12.8 12.8 in C6= 2.7 2.7 2.7 2.7 in

Amount of energy dissipated with no permanent damage:

Energy dissipated:

Energy dissipated:

Barrier equivalent velocity: BEV

Barrier equivalent velocity:

G=	584.2	463.3	696.7	579.4	lbs
E=	7775569	5808091	11154328	8245751	in-lbs
	647964	484008	929527	687146	ft-lbs
EV=	88.2	76.2	105.6	90.8	ft/s
	60.0	51.8	71.8	61.8	mph

$$E = \frac{W}{5} \left[ 5G + \frac{A}{2} (C_1 + 2C_2 + 2C_3 + 2C_4 + 2C_5 + C_6) + \frac{B}{6} (C_1^2 + 2C_2^2 + 2C_3^2 + 2C_4^2 + 2C_5^2 + C_6^2 + C_1C_2 + C_2C_3 + C_3C_4 + C_4C_5 + C_5C_6) \right] (1 + (\tan \theta)^2)$$

$$V = \sqrt{\frac{2gE}{W}}$$



lb/in

lbs

in

in

lb/in/in

degrees

# **Depict and Analyze EDR data**

Reported Values					Calculated Values					
TRG 1 -	TRG 6 -		Accelerator		ABS Control					
Time	Time	Vehicle Speed	Pedal, % Full	Service Brake	Status	Steering Input	Yaw Rate	Vehicle Speed	Acceleration	Drag Factor
-4.95 s		116.8 mph	89.5%	OFF	OFF	4.5° (Left)	0.00 deg/s	171.3 fps		
									0.0 fps <sup>2</sup>	0.00
-4.45 s		116.8 mph	89.5%	OFF	OFF	3.0° (Left)	-0.49 deg/s	171.3 fps		
									1.8 fps <sup>2</sup>	-0.05
-3.95 s		117.4 mph	80.5%	OFF	OFF	3.0° (Left)	-1.46 deg/s	172.2 fps		
2.45	4.00	447.4	40.50/	055	055	2.00/1.61	0.00   /	472.26	0.0 fps <sup>2</sup>	0.00
-3.45 s	-4.80 s	117.4 mph	49.5%	OFF	OFF	3.0° (Left)	-0.98 deg/s	172.2 fps	2563	2.11
2.05 -	4 20 -	116.2	0.00/	OFF	OFF	2.0% /1 -61	0.40/-	170 F f	-3.5 fps <sup>2</sup>	0.11
-2.95 s	-4.30 s	116.2 mph	0.0%	OFF	OFF	3.0° (Left)	-0.49 deg/s	170.5 fps	-3.5 fps <sup>2</sup>	0.11
-2.45 s	-3.80 s	115.0 mph	0.0%	ON	OFF	3.0° (Left)	-0.49 deg/s	168.7 fps	-3.5 ips	0.11
-2.433	3.003	115.0 mpn	0.070	ON	OH	3.0 (2011)	-0.45 deg/s	100.7 103	-3.8 fps <sup>2</sup>	0.12
-1.95 s	-3.30 s	113.7 mph	0.0%	ON	OFF	3.0° (Left)	-0.49 deg/s	166.8 fps	0.0.,60	0.12
						(			-3.5 fps <sup>2</sup>	0.11
-1.45 s	-2.80 s	112.5 mph	0.0%	ON	OFF	6.0° (Left)	0.00 deg/s	165.0 fps	·	
									-3.8 fps <sup>2</sup>	0.12
-0.95 s	-2.30 s	111.2 mph	0.0%	ON	OFF	12.0° (Left)	2.93 deg/s	163.1 fps		
									-1.8 fps <sup>2</sup>	0.05
-0.45 s	-1.80 s	110.6 mph	0.0%	ON	OFF	24.0° (Left)	6.34 deg/s	162.3 fps		
									-9.1 fps²	0.28
	-1.30 s	107.5 mph	0.0%	ON	OFF	52.5° (Left)	15.62 deg/s	157.7 fps		
		004		<b></b>		40.00 (1.6)		100.05	-51.1 fps <sup>2</sup>	1.59
	-0.80 s	90.1 mph	0.0%	ON	ON	12.5° (Left)	9.76 deg/s	132.2 fps	10.2 fmc?	0.56
	-0.30 s	83.9 mph	82.5%	ON	ON	127.5° (Left)	22.45 deg/s	123.1 fps	-18.2 fps <sup>2</sup>	0.56
	-0.50 \$	65.5 mpn	02.370	ON	ON	127.5 (Left)	22.45 deg/s	125.1 lps	-82.2 fps <sup>2</sup>	2.55
IMPACT	0.00 s	67.1 mph	33.5%	ON	ON	133.5° (Left)	Invalid	98.4 fps	-02.2 103	2.55
IIVIPACI	0.00 \$	67.1 mph	55.5%	UN	UN	133.5 (Left)	invalid	98.4 TPS		



# **Create templates**

Weight	W
Pre-impact velocity	V
Pre-impact velocity	V
Post-impact velocity	<i>v'</i>
Post-impact velocity	<i>v'</i>
Pre-impact momentum	P
Post-Impact momentum	P'
Delta-v (x-direction earth based)	∆v - x
Delta-v (y-direction earth based)	∆v - y
Delta-v total	$\Delta v$
Delta-v total	$\Delta v$
Pre-impact angle	Θ
Post-impact angle	$\Theta'$
Direction change	$\Delta\Theta$
Principal direction of force - earth based	PDOF-Earth
Principal direction of force - vehicle based	PDOF-Vehicle
Principal direction of force - clock based	PDOF-Vehicle

		_
Chrysler	Ford	
4285	4995	lbs
27.9	43.4	ft/s
19.0	29.6	mi/hr
26.9	26.9	ft/s
18.3	18.3	mi/hr
119703	216637	(lb ft)/s
115267	134366	(lb ft)/s
-11.7	10.1	ft/s
-21.5	18.4	ft/s
24.5	21.0	ft/s
17	14	mi/hr
0.0	270.0	degrees
307.0	292.0	degrees
61.3	61.3	degrees
241.3	61.3	degrees
-61.3	28.7	degrees
10:00	1:00	clockface

Δv - x vehicle	Delta-v direction (longitudinal)
Δv - y vehicle	Delta-v direction (lateral)
arphi	Angle adjustment
Δv - x vehicle	Delta-v (longitudinal)
Δv - y vehicle	Delta-v (lateral)

Delta-v (lateral)

Delta-v (longitudinal)

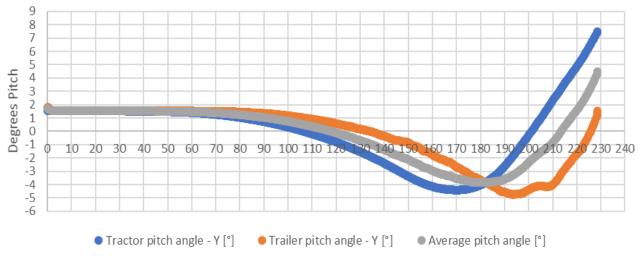
		_
Negative	Negative	[SAE]
Positive	Negative	[SAE]
118.7	-151.3	degrees
-11.7	-18.4	ft/s
21.5	-10.1	ft/s
-8.0	-12.6	mi/hr
14.6	-6.9	mi/hr

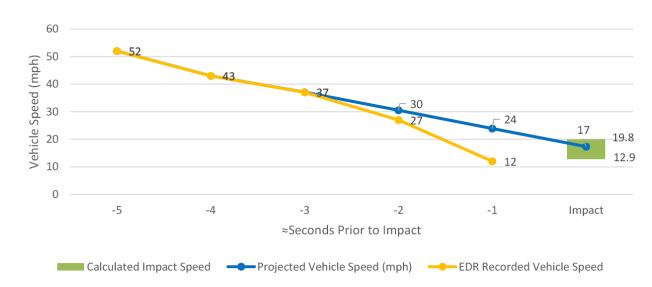


Δv - x vehicle

Δv - y vehicle

# **Graph your findings**







# **Excel Interface**

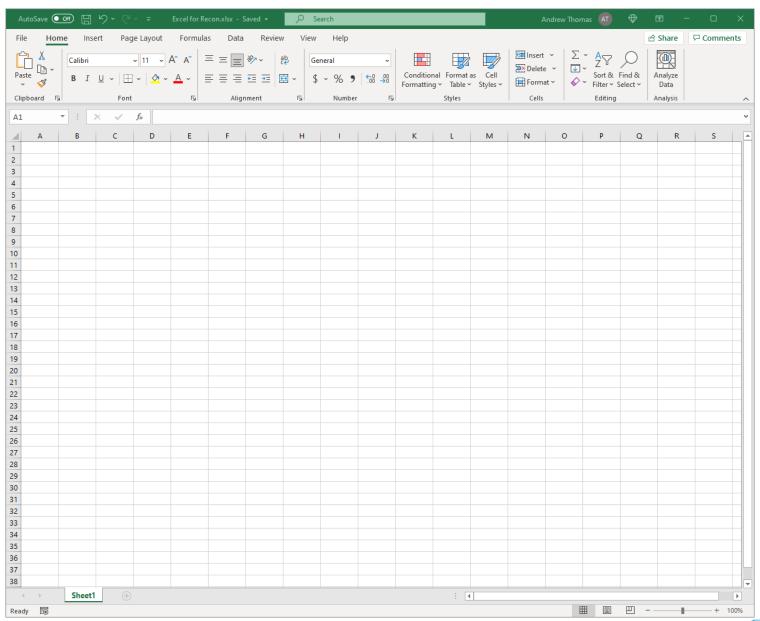
**Excel for Crash Reconstruction** 





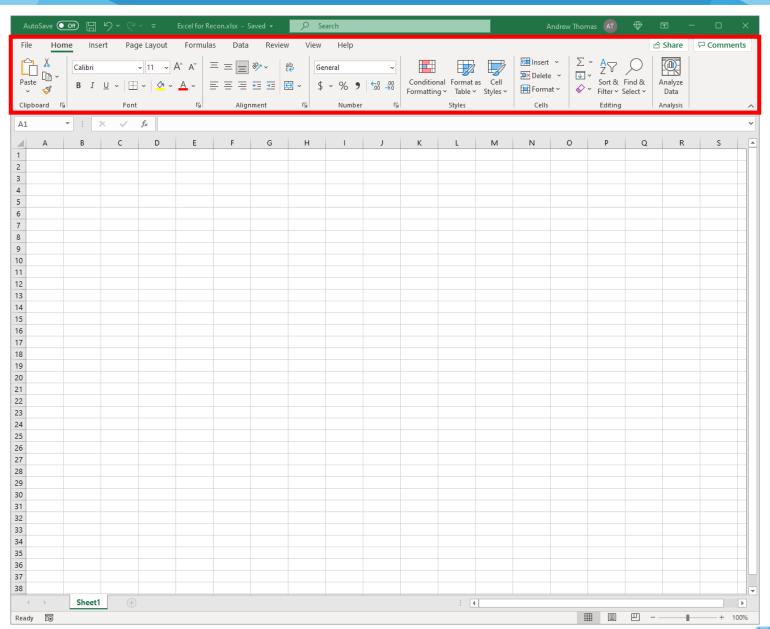


#### **Excel Interface**



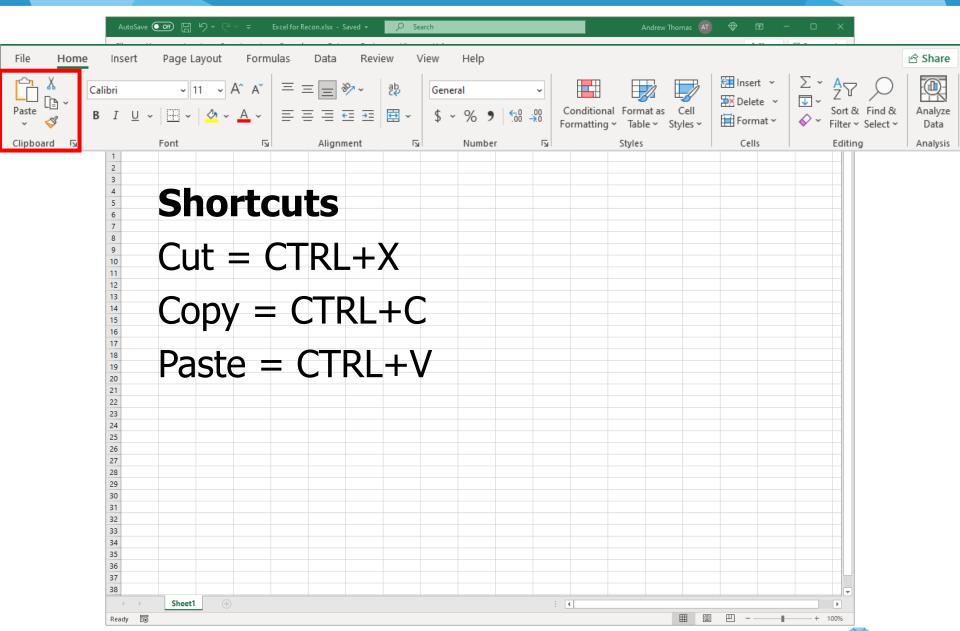






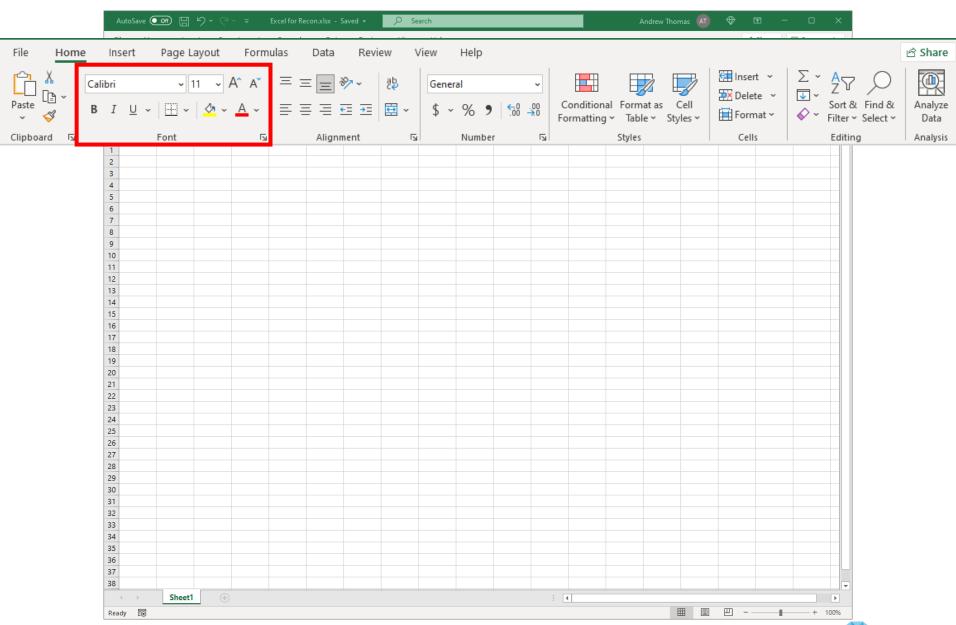






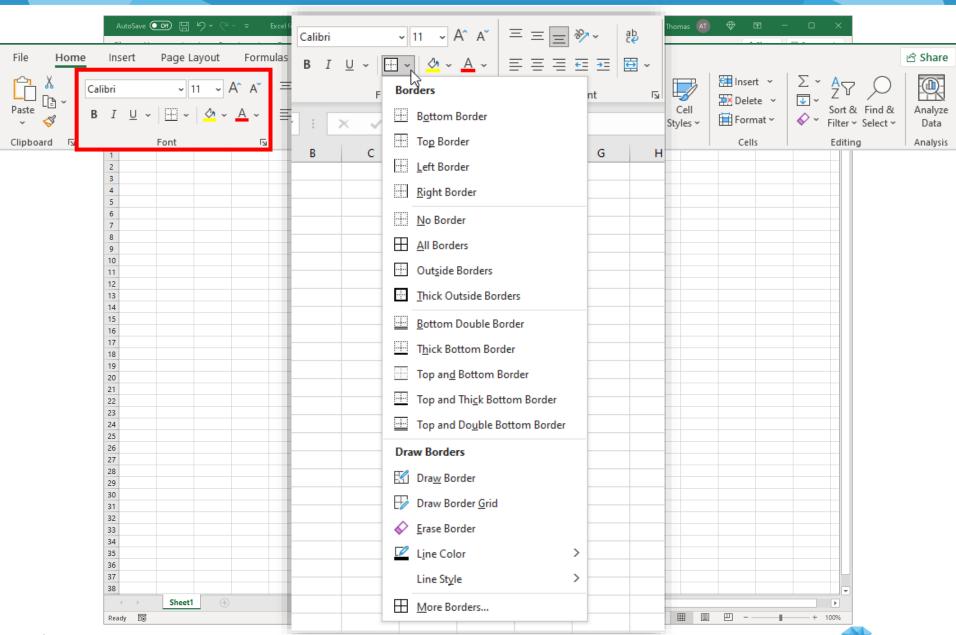




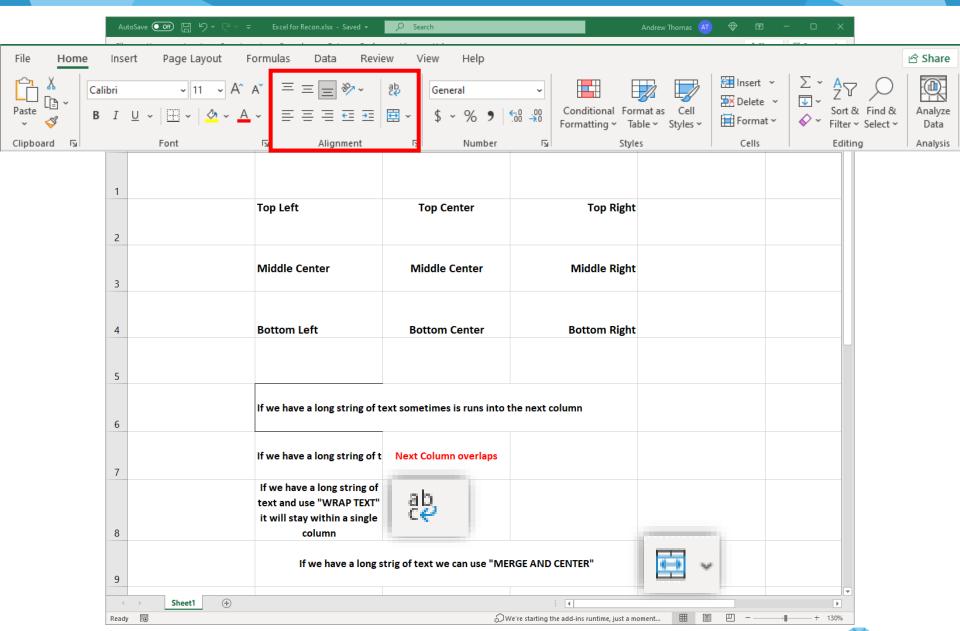




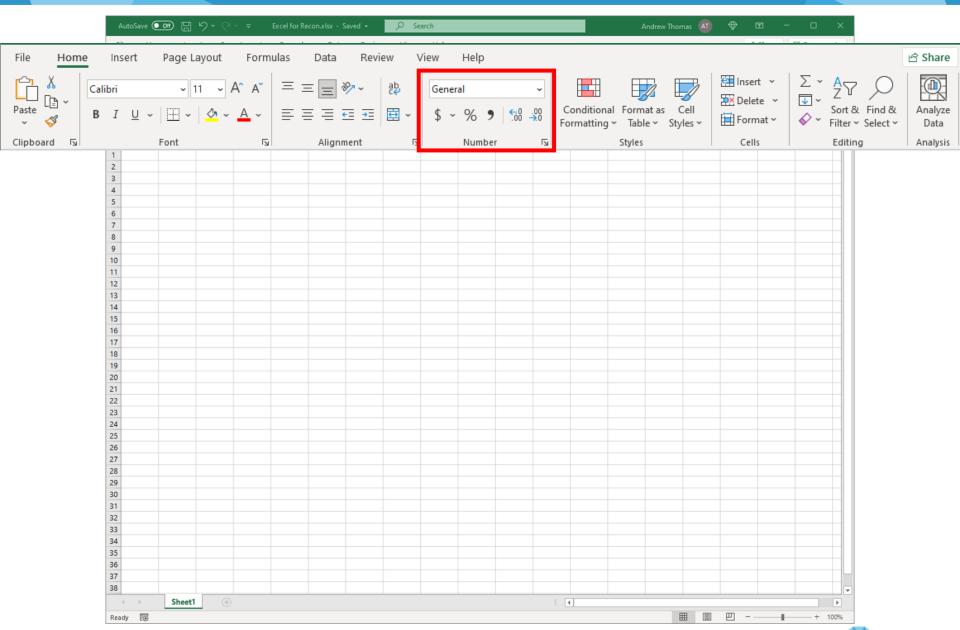




Analytics

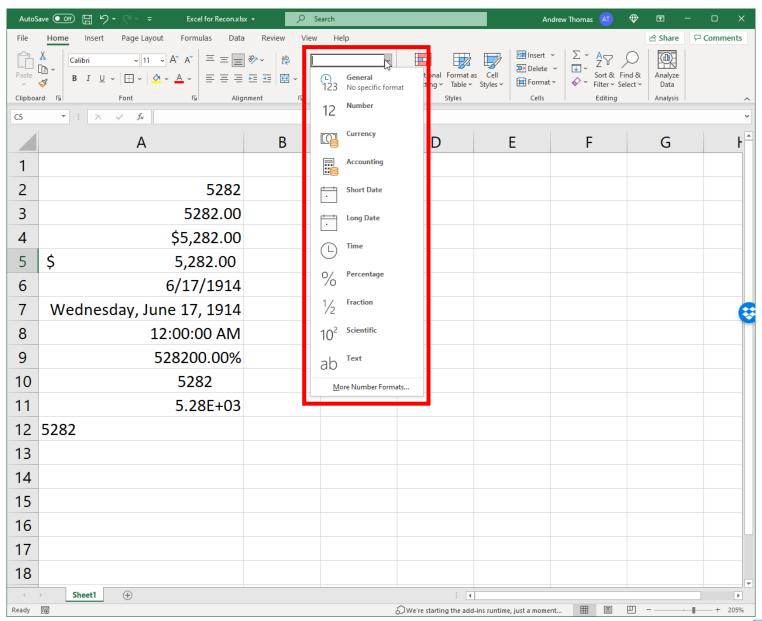




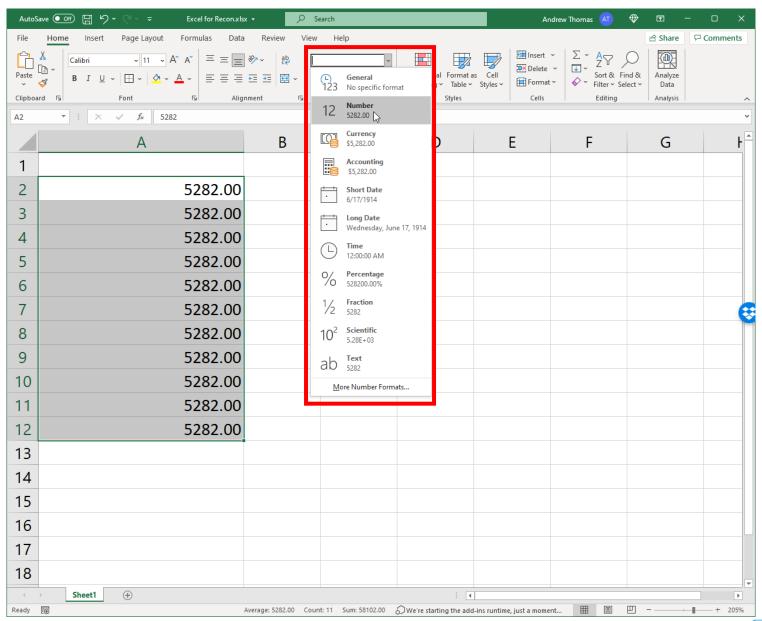




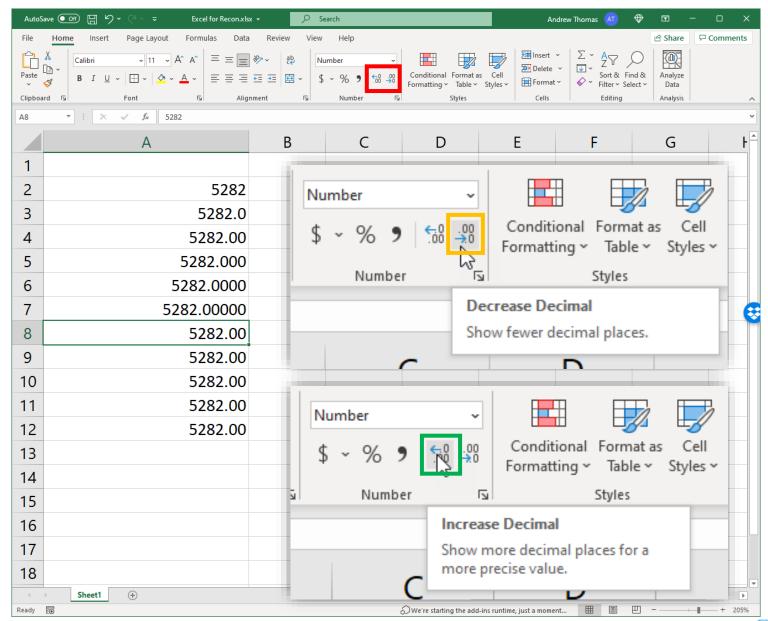




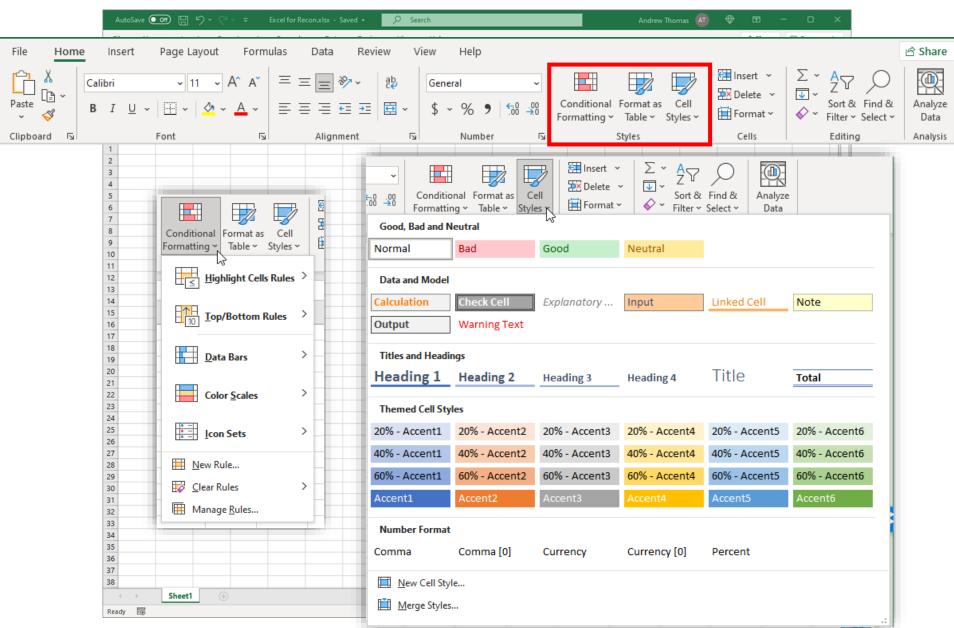






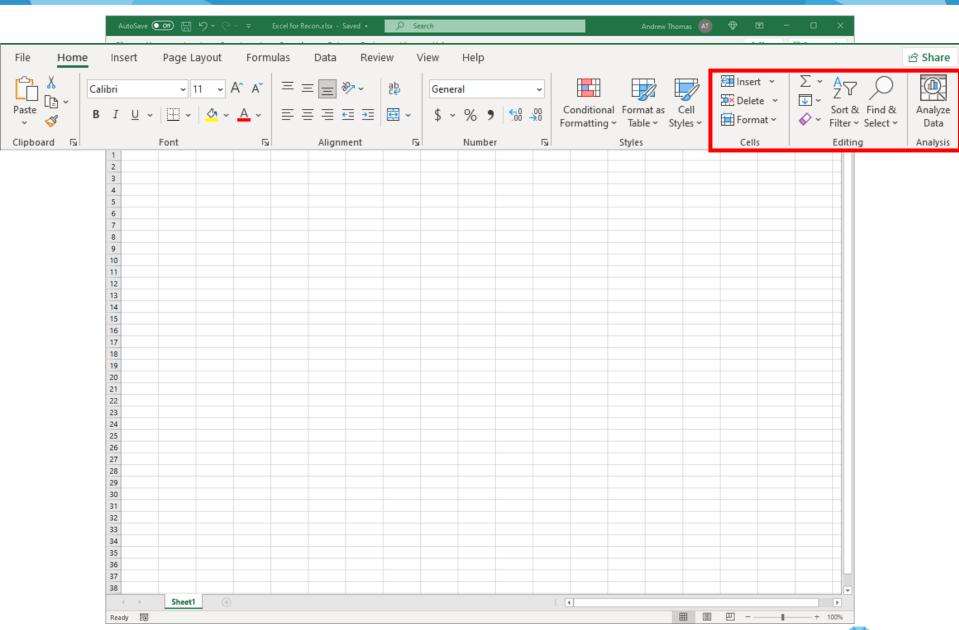






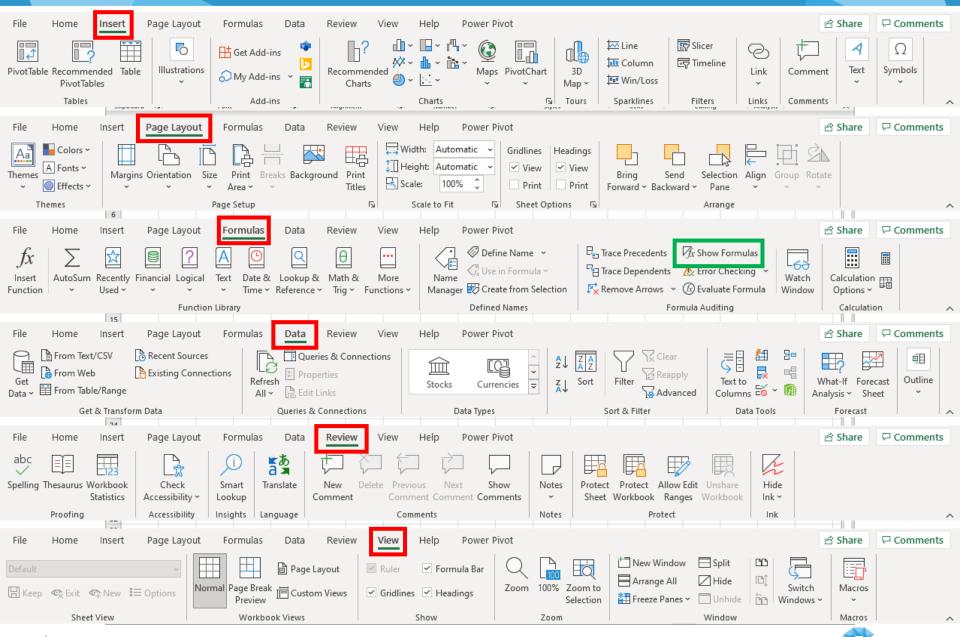




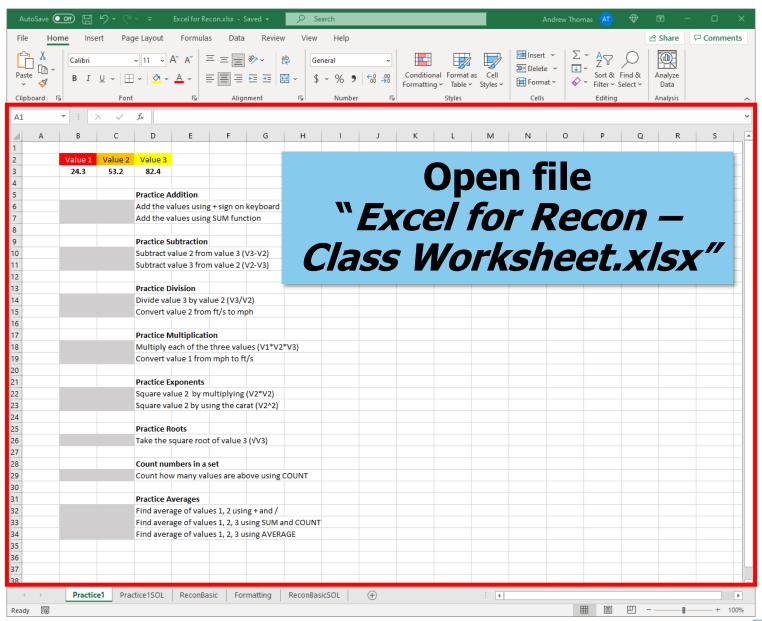




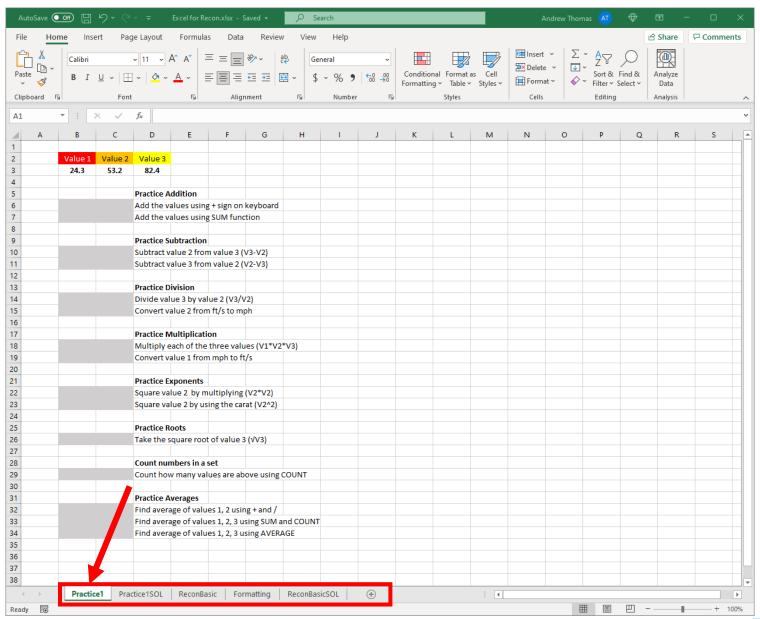




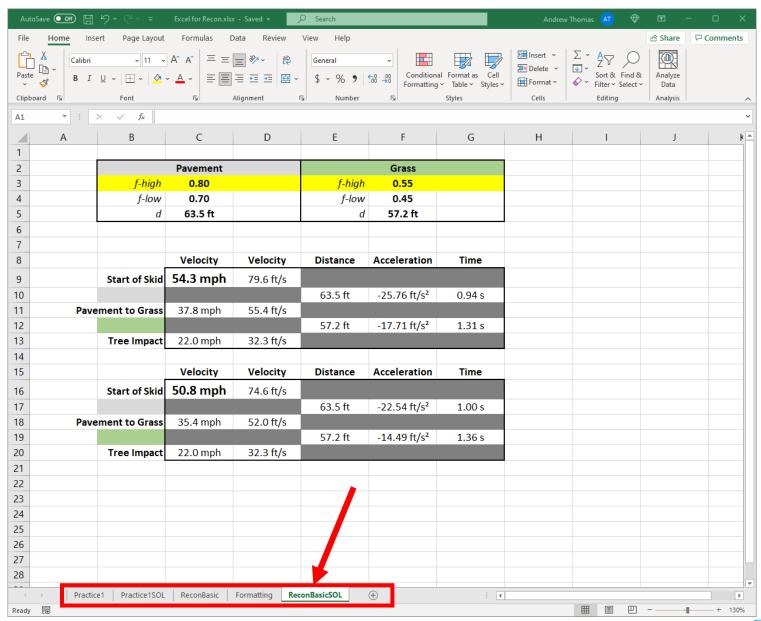
Analytics



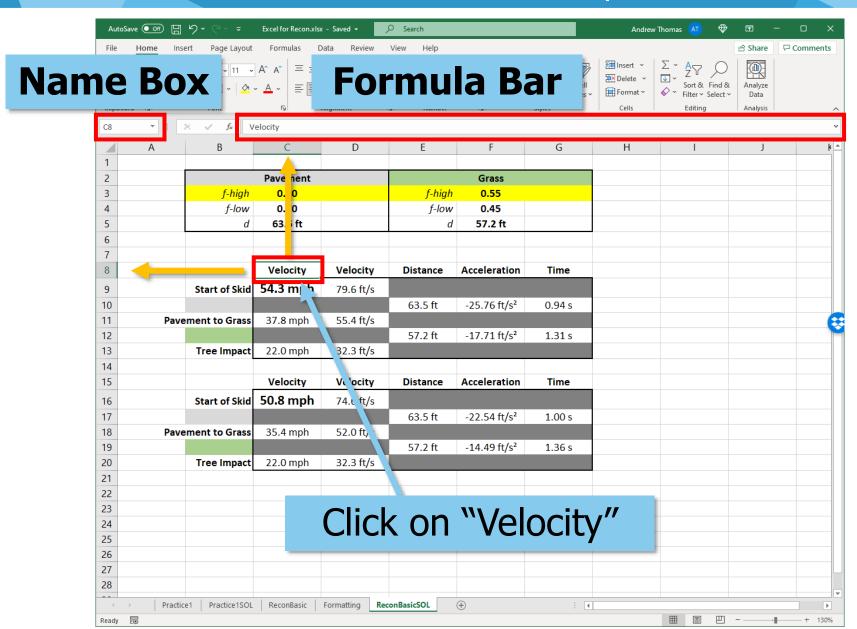




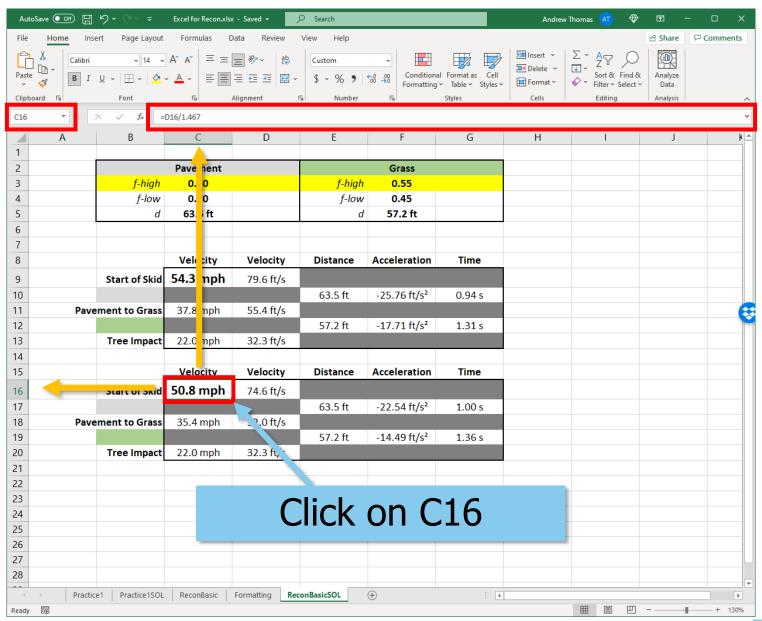




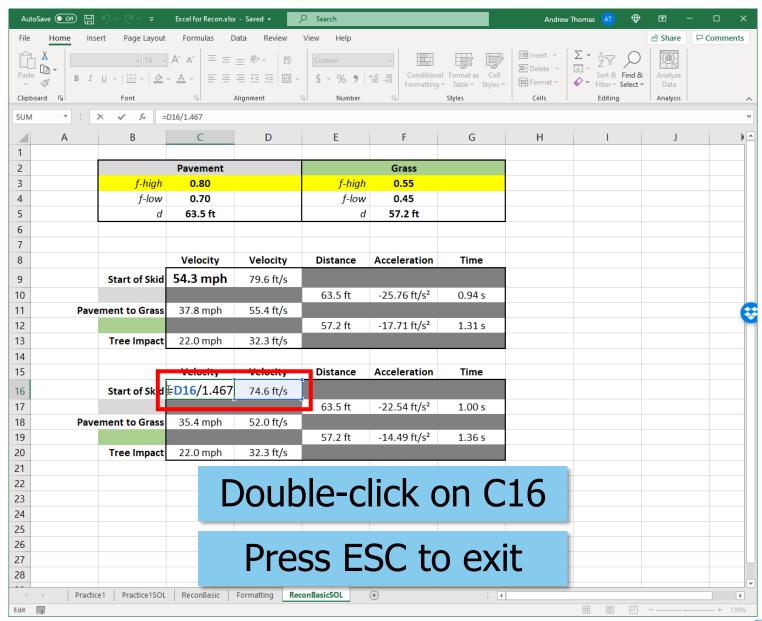




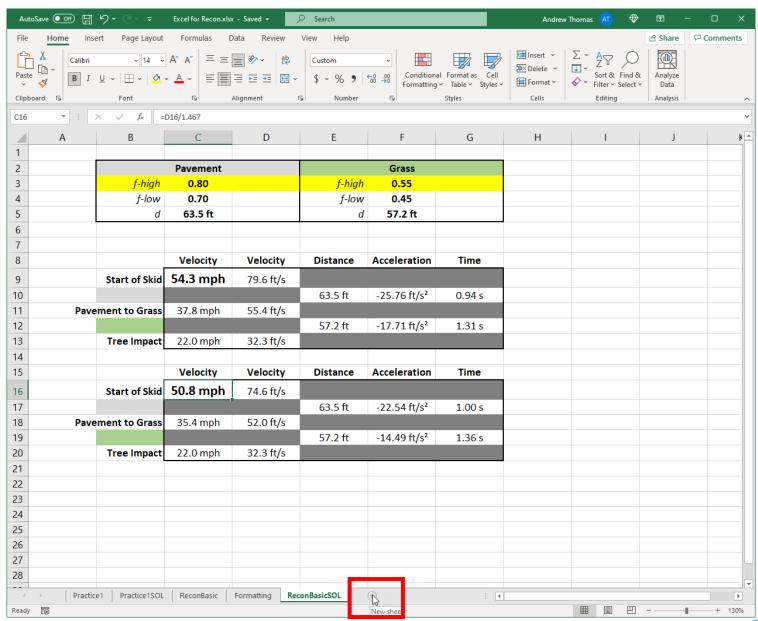




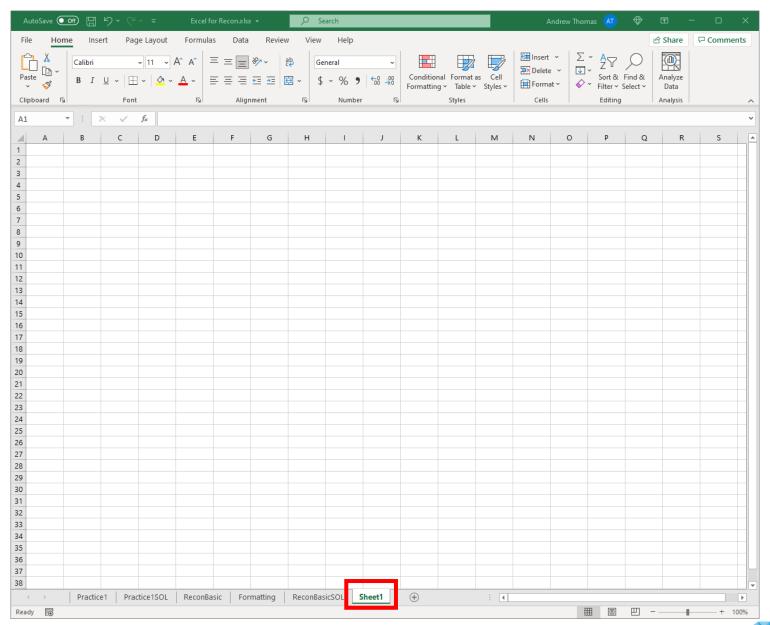




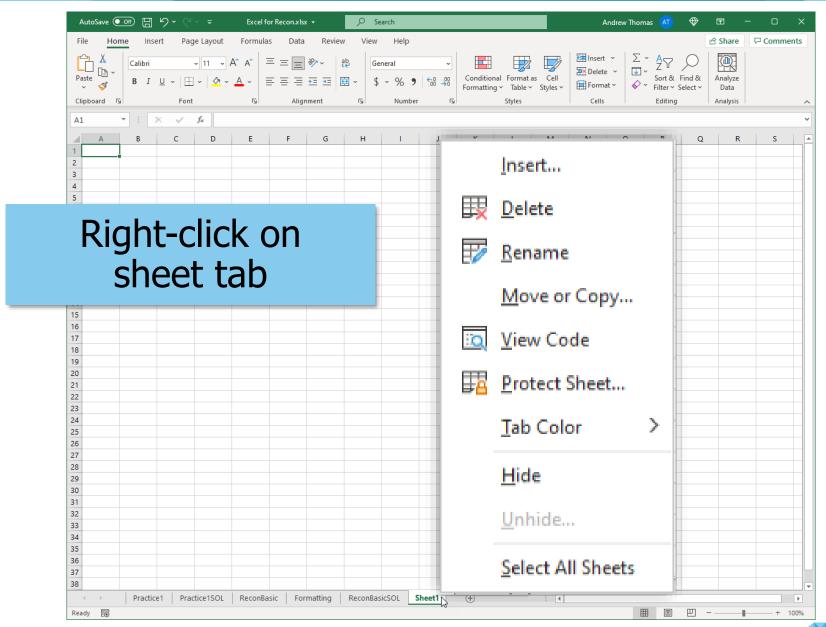


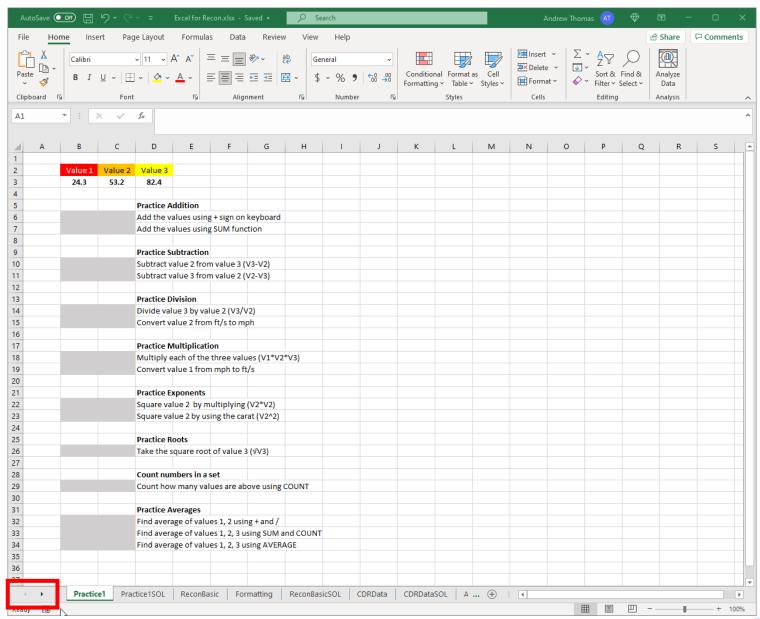














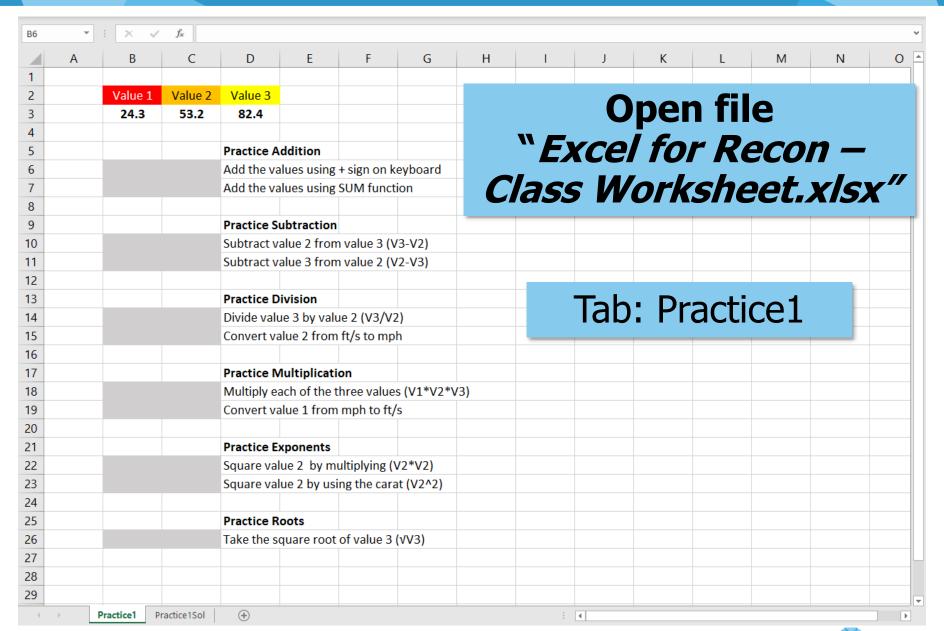
# **Formula Basics**

**Excel for Crash Reconstruction** 



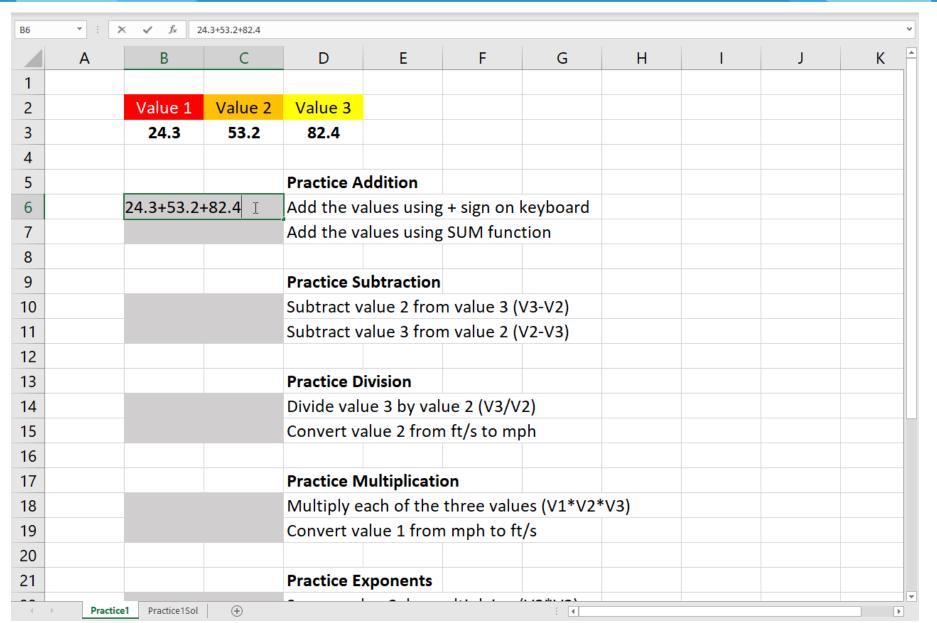


#### Formula Basics

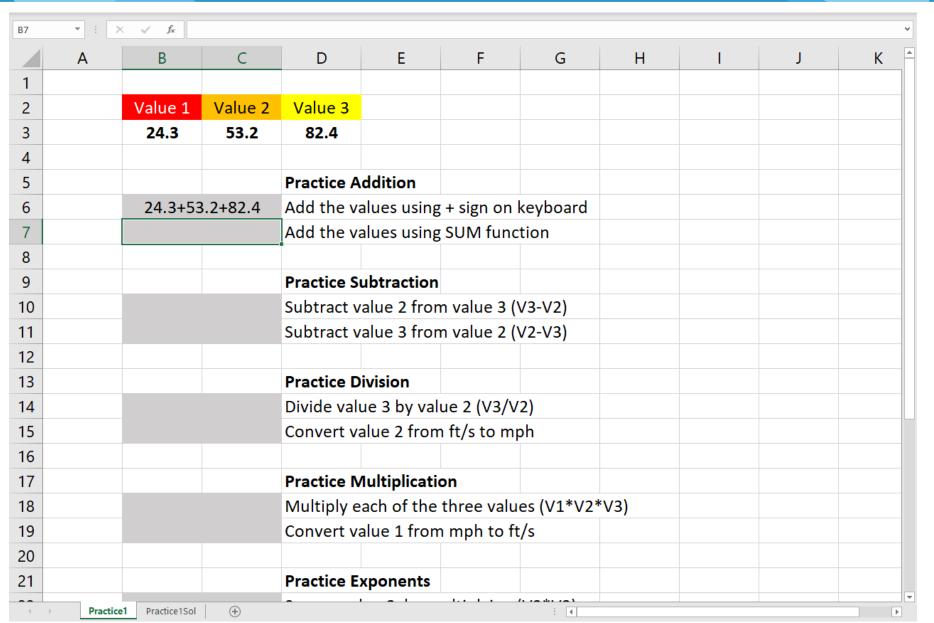




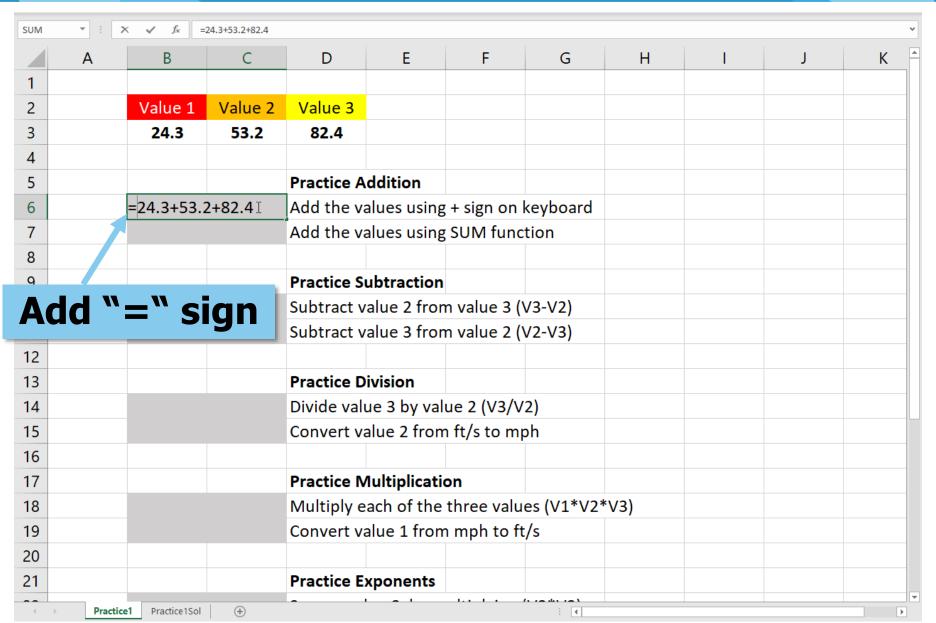
#### Formula Basics



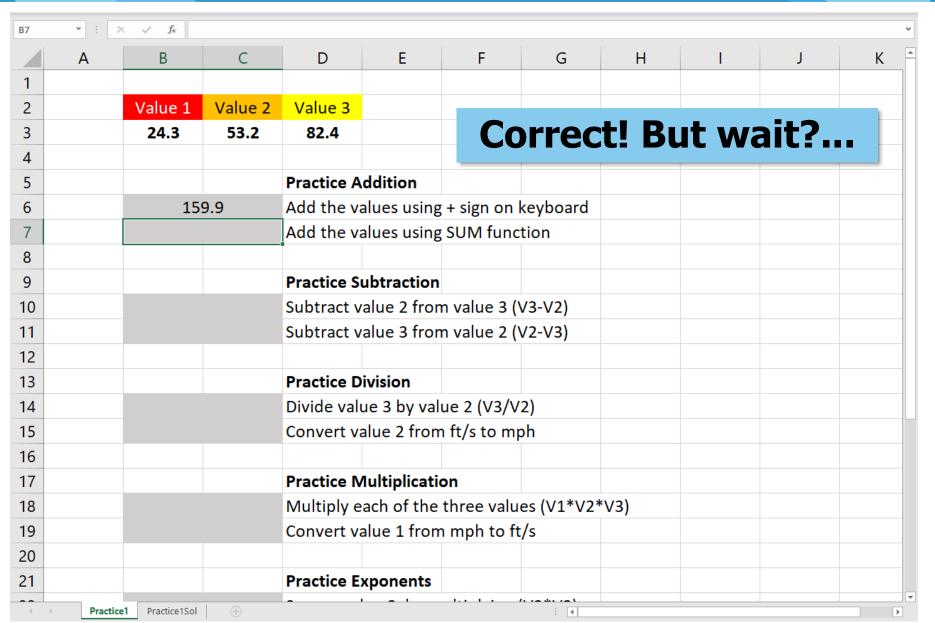














B6	<b>Y</b>     >		24.3+53.2+82.4										
4	Α	В	С	D	Е	F	G	Н	1	J	K		
1													
2		Value 1	Value 2	Value 3									
3		24.3	53.2	100									
4													
5				Practice A									
6		159	9.9	Add the v	Add the values using + sign on keyboard								
7				Add the v	alues using	SUM fund	tion						
8													
9				Practice S	ubtraction								
10				Subtract v	alue 2 fron	n value 3 (	V3-V2)						
11				Subtract v	alue 3 fron	n value 2 (	V2-V3)						
12													
13				Practice D	ivision								
14				Divide val	ue 3 by val	ue 2 (V3/V	2)						
15				Convert v	alue 2 from	ft/s to m	oh						
16													
17				Practice N	/lultiplication	on							
18				Multiply e	ach of the	three valu	es (V1*V2*	'V3)					
19				Convert va	alue 1 from	mph to ft	:/s						
20													
21				Practice E	xponents								



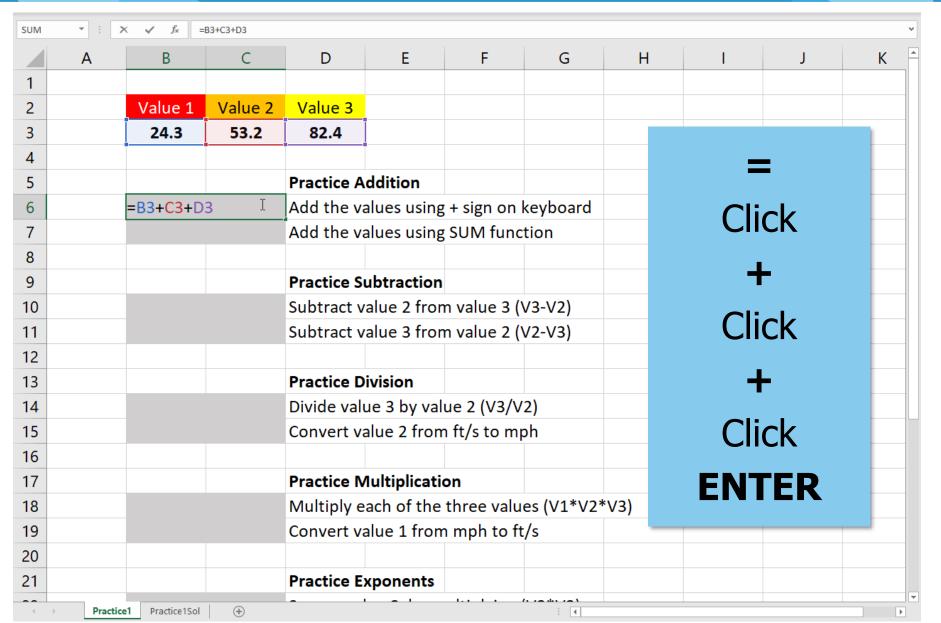
SUM			24.3+53.2+82.4										
4	Α	В	С	D	Е	F	G	Н	I	J	K		
1													
2		Value 1	Value 2	Value 3									
3		24.3	53.2	100									
4													
5				Practice A	ddition								
6		=24.3+53.2	2+82.4	Add the v	Add the values using + sign on keyboard								
7				Add the v	alues using	SUM fund	tion						
8													
9				Practice S	ubtraction								
10				Subtract v	alue 2 fron	n value 3 (	V3-V2)						
11				Subtract v	alue 3 fron	n value 2 (	V2-V3)						
12													
13				Practice D	ivision								
14				Divide val	ue 3 by valı	ue 2 (V3/V	2)						
15				Convert va	alue 2 from	ft/s to m	oh						
16													
17				Practice N	1ultiplication	on							
18				Multiply e	ach of the	three valu	es (V1*V2*	'V3)					
19				Convert va	alue 1 from	mph to ft	:/s						
20													
21				Practice E	xponents								









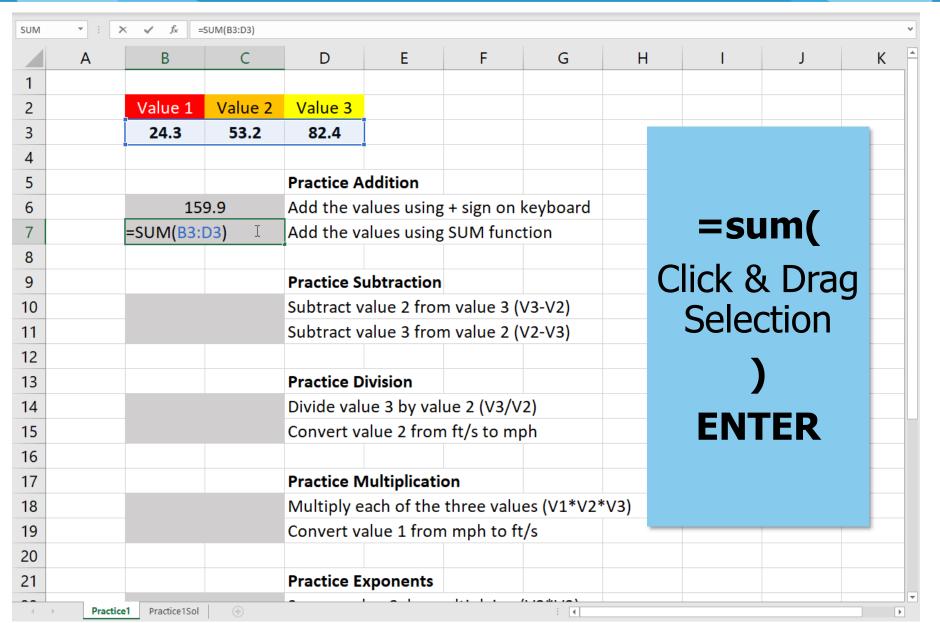




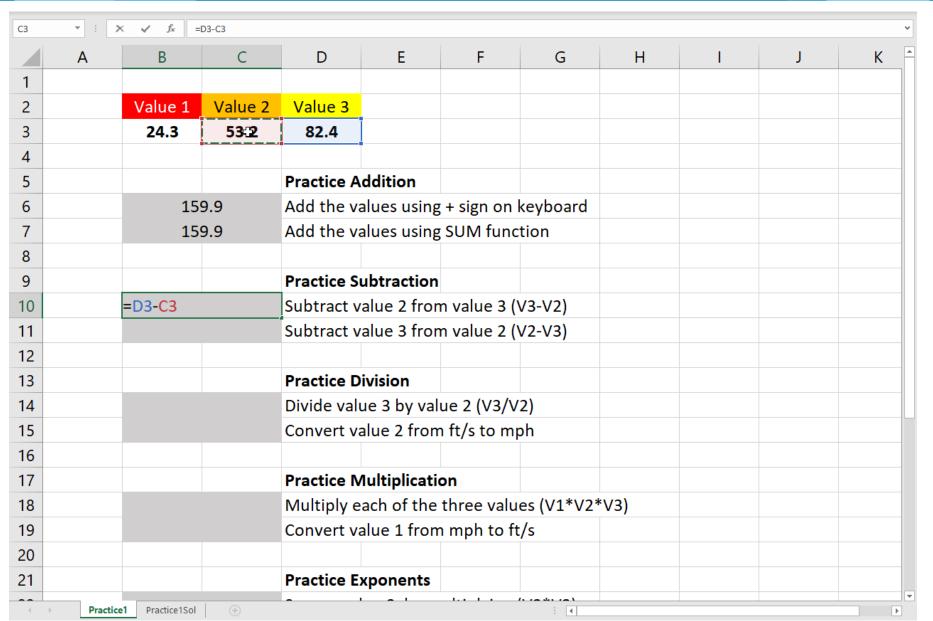




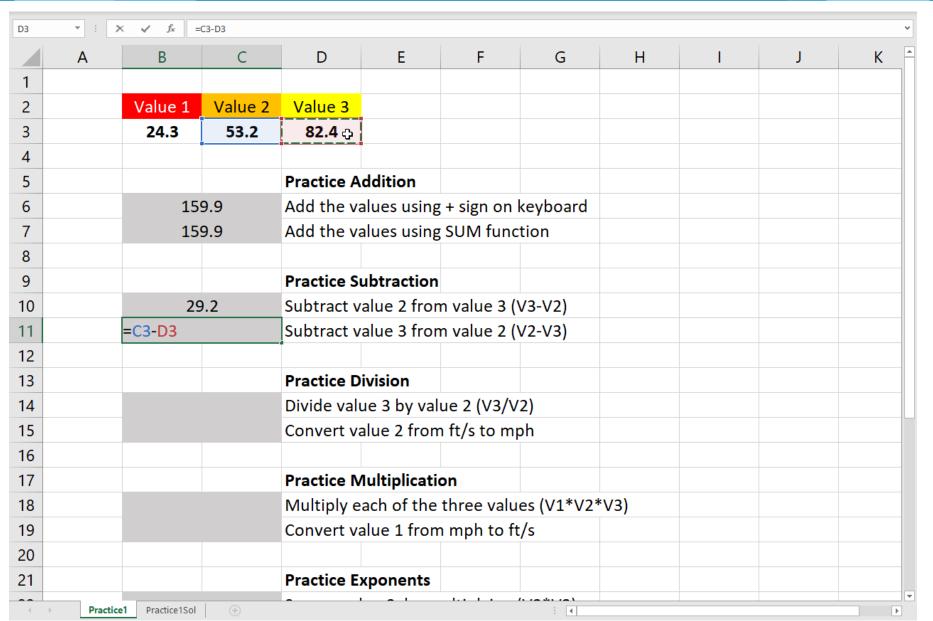








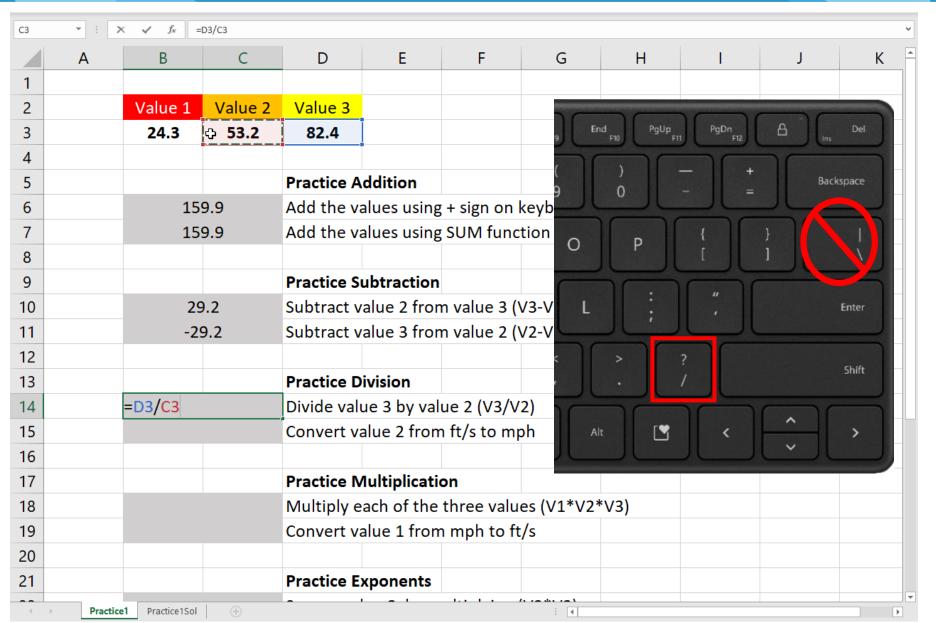




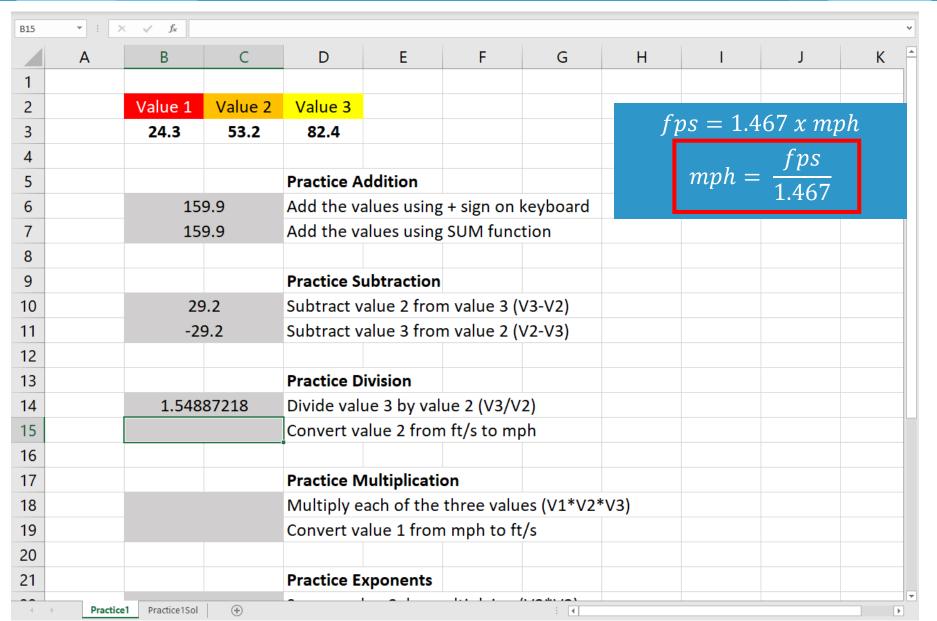


B12	_ +	√ f <sub>x</sub>									
	Α	В	С	D	Е	F	G	Н	1	J	K
1											
2		Value 1	Value 2	Value 3							
3		24.3	53.2	82.4							
4											
5				Practice A	ddition						
6		15	9.9	Add the v	alues using	+ sign on	keyboard				
7		15	9.9	Add the v	alues using	SUM fund	tion				
8											
9				Practice S	ubtraction						
10		29	9.2	Subtract value 2 from value 3 (V3-V2)							
11		-29	9.2	Subtract value 3 from value 2 (V2-V3)							
12											
13				Practice D	ivision						
14				Divide val	ue 3 by val	ue 2 (V3/V	2)				
15				Convert v	alue 2 from	ft/s to m	oh				
16											
17				Practice N	1ultiplication	on					
18				Multiply e	ach of the	three valu	es (V1*V2*	·V3)			
19				Convert v	alue 1 from	mph to f	:/s				
20											
21				Practice E	xponents						

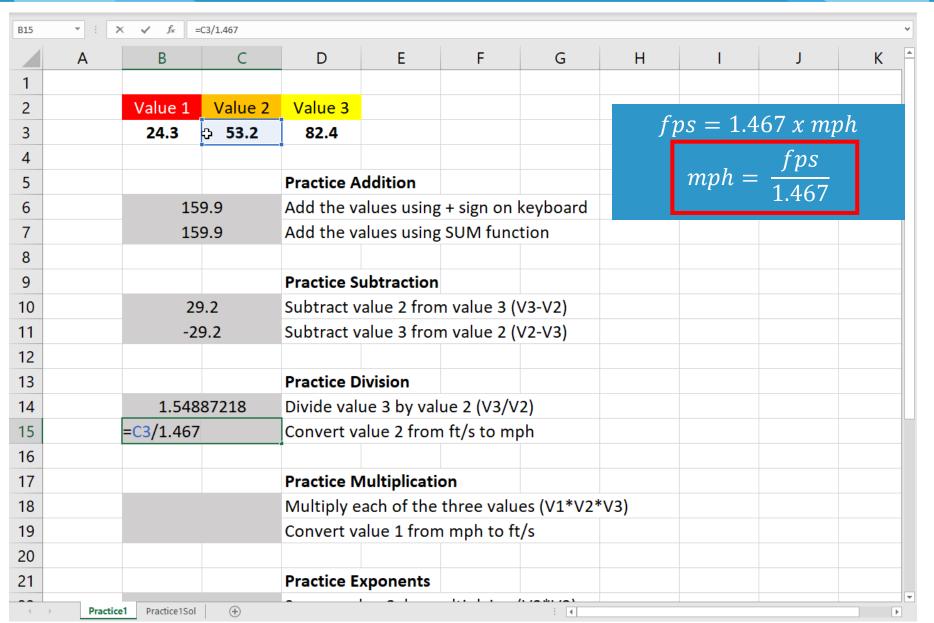








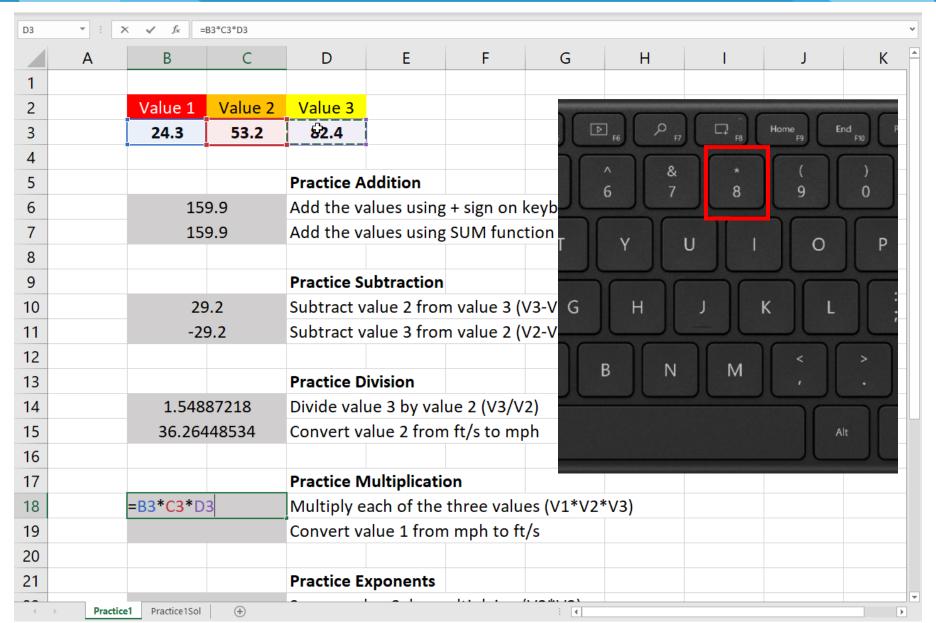




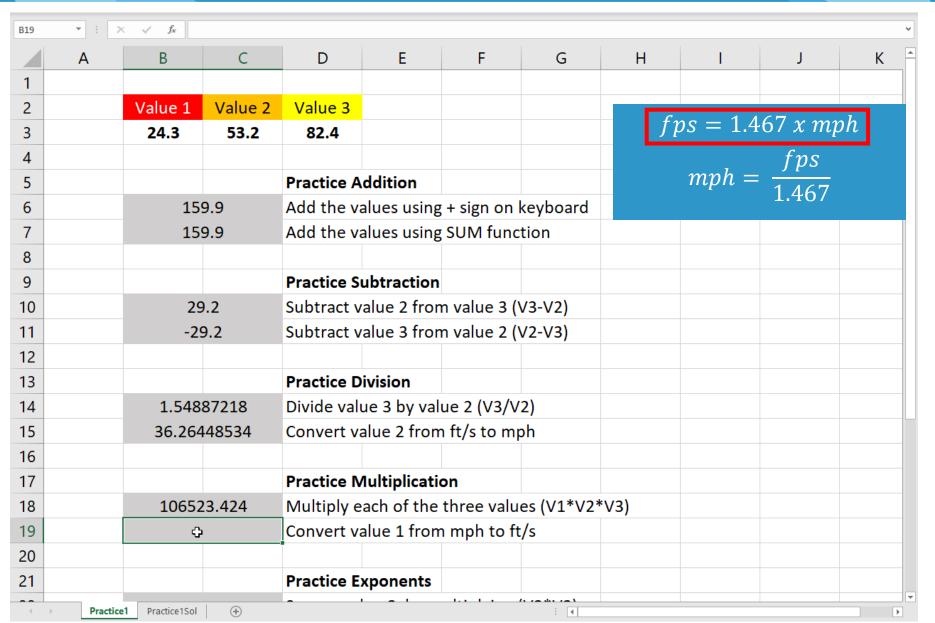


B15	<b>T</b> : >	√ f <sub>x</sub> =	C3/1.467									
	Α	В	С	D	Е	F	G	Н	I	J	K	
1												
2		Value 1	Value 2	Value 3								
3		24.3	53.2	82.4								
4												
5				Practice A	ddition							
6		15	9.9	Add the v	Add the values using + sign on keyboard							
7		15	9.9	Add the v	alues using	SUM func	tion					
8												
9				Practice S	ubtraction							
10		29	9.2	Subtract value 2 from value 3 (V3-V2)								
11		-29	9.2	Subtract v	alue 3 fron	n value 2 (	V2-V3)					
12												
13				Practice D	ivision							
14		1.548	87218	Divide val								
15		36.264	148534	Convert v	alue 2 from	ft/s to m	oh					
16												
17				Practice N	1ultiplication	on						
18				Multiply e	ach of the	three valu	es (V1*V2*	*V3)				
19				Convert va	alue 1 from	mph to ft	:/s					
20												
21				Practice E	xponents							
+ +	Practice	Practice1Sol	+	_		1.1.1						

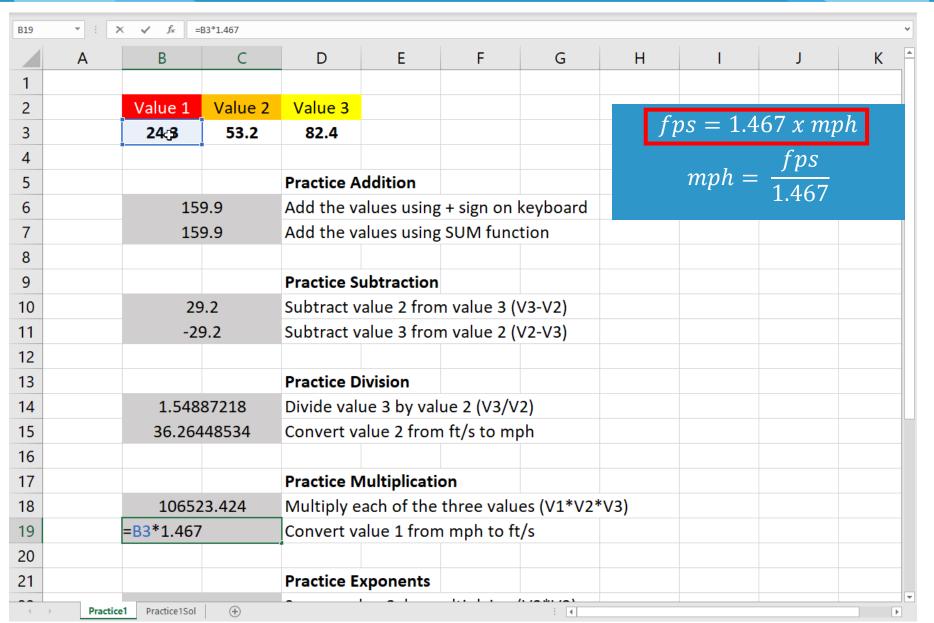








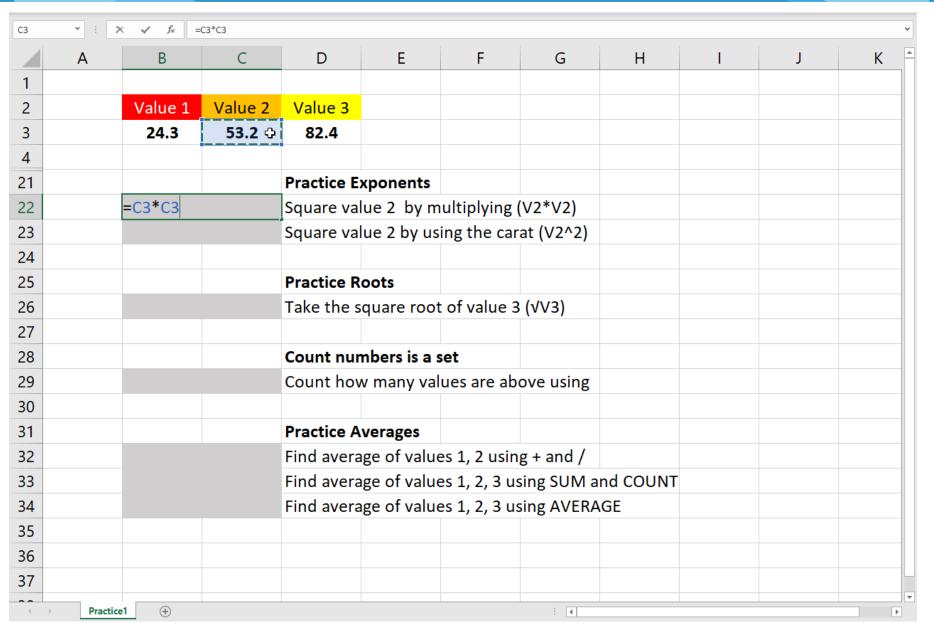




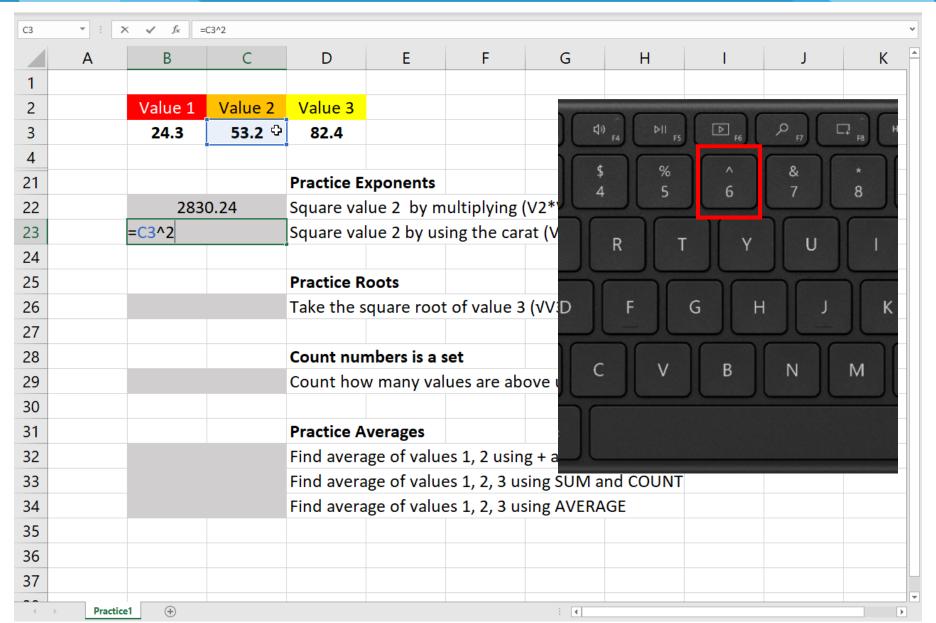


B20	<b>T</b> :   >	√ f <sub>x</sub>									
	Α	В	С	D	Е	F	G	Н	I	J	K
1											
2		Value 1	Value 2	Value 3							
3		24.3	53.2	82.4							
4											
5				Practice A	ddition						
6		15	9.9	Add the v	alues using	+ sign on	keyboard				
7		15	9.9	Add the v	alues using	SUM fund	tion				
8											
9				<b>Practice S</b>	ubtraction						
10		29	9.2	Subtract value 2 from value 3 (V3-V2)							
11		-29	9.2	Subtract v	alue 3 fron	n value 2 (	V2-V3)				
12											
13				Practice D	ivision						
14		1.548	87218	Divide val	ue 3 by val	ue 2 (V3/V	2)				
15		36.264	148534	Convert v	alue 2 from	n ft/s to m	ph				
16											
17				Practice N	1ultiplication	on					
18		10652	23.424	Multiply e	ach of the	three valu	es (V1*V2*	'V3)			
19		35.6	481	Convert v	alue 1 from	mph to fi	t/s				
20											
21				Practice E	xponents						
	Practice	Practice1Sol	+	-		1.1 1 1	() (a) (a) (b) (d)				

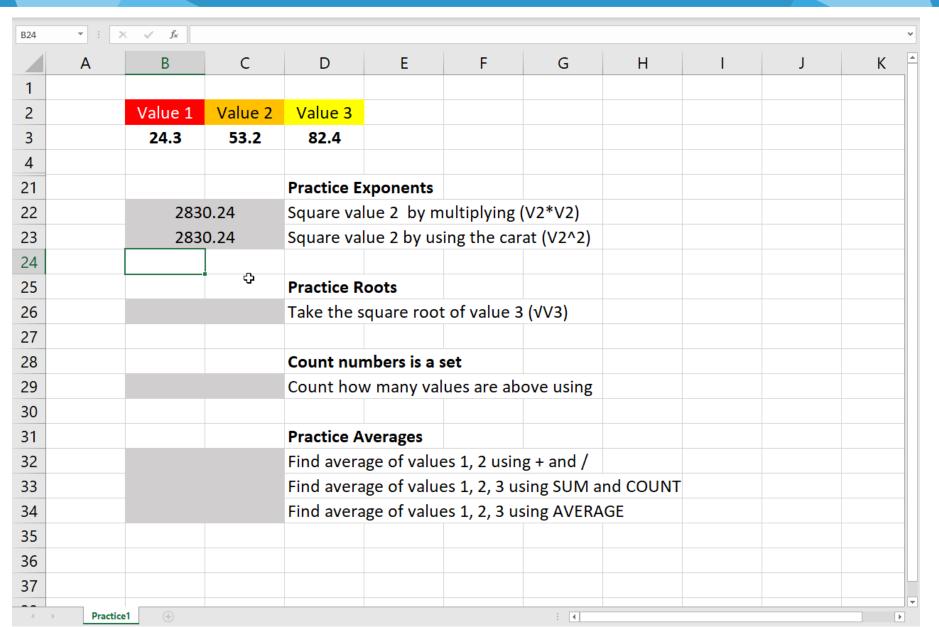




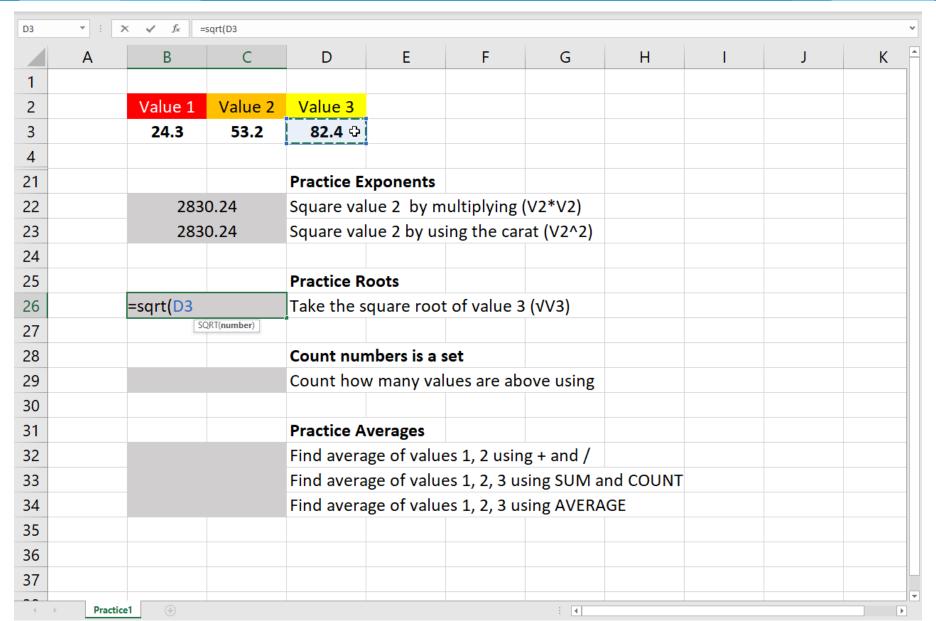








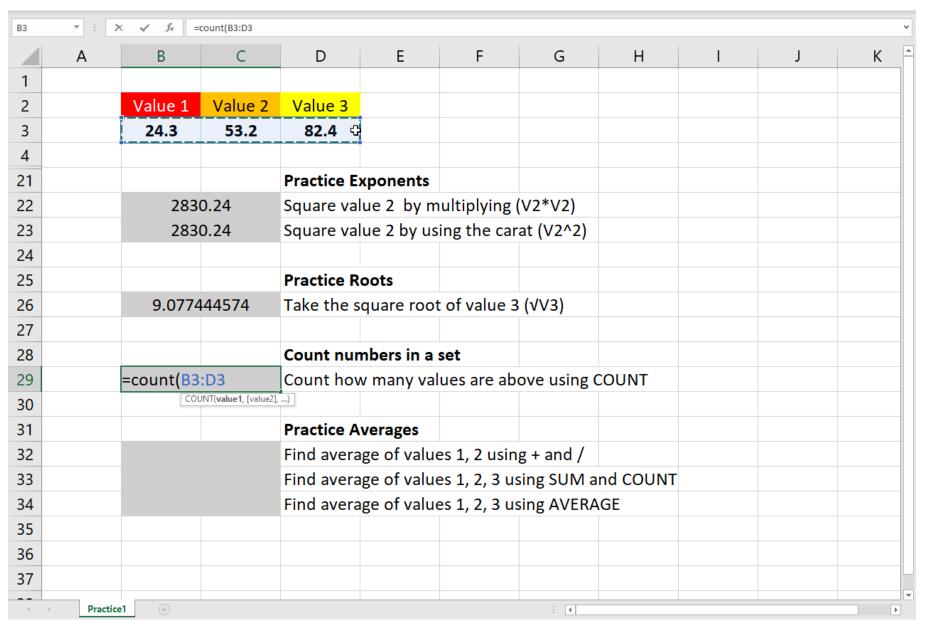




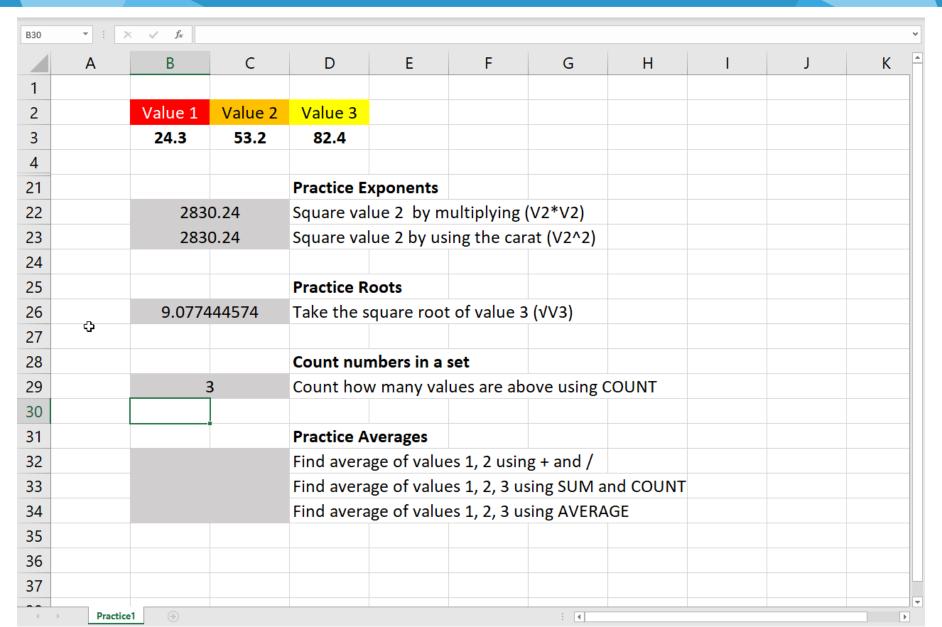


B27	▼ : ;	× \( \sqrt{f_x}										
	Α	В	С	D	E	F	G	Н	1	J	K	
1												
2		Value 1	Value 2	Value 3								
3		24.3	53.2	82.4								
4												
21				Practice E	xponents							
22		283	0.24	Square va	lue 2 by m	nultiplying	(V2*V2)					
23		283	0.24	Square va	lue 2 by us	ing the car	at (V2^2)					
24												
25				Practice R	ictice Roots							
26		9.0774	144574	Take the s	quare roo	t of value 3	3 (√√3)					
27												
28				Count nur	mbers in a	set						
29				Count hov	w many va	lues are ab	ove using C	COUNT				
30												
31				Practice A	verages							
32				Find avera	age of value	es 1, 2 usin	g + and /					
33				Find avera	age of value	es 1, 2, 3 u	sing SUM a	nd COUNT				
34				Find avera	ge of valu	es 1, 2, 3 u	sing AVERA	GE				
35												
36												
37												

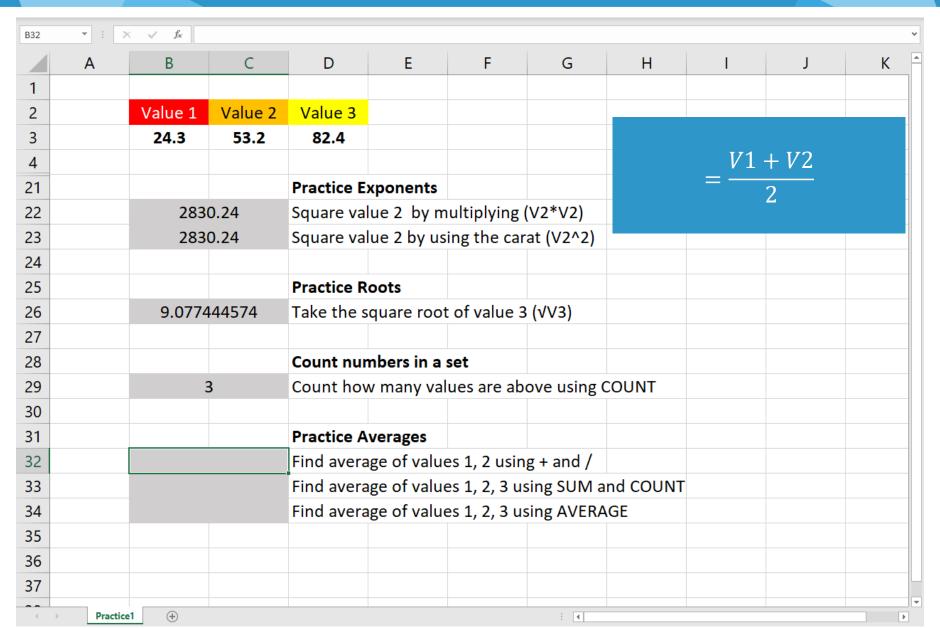




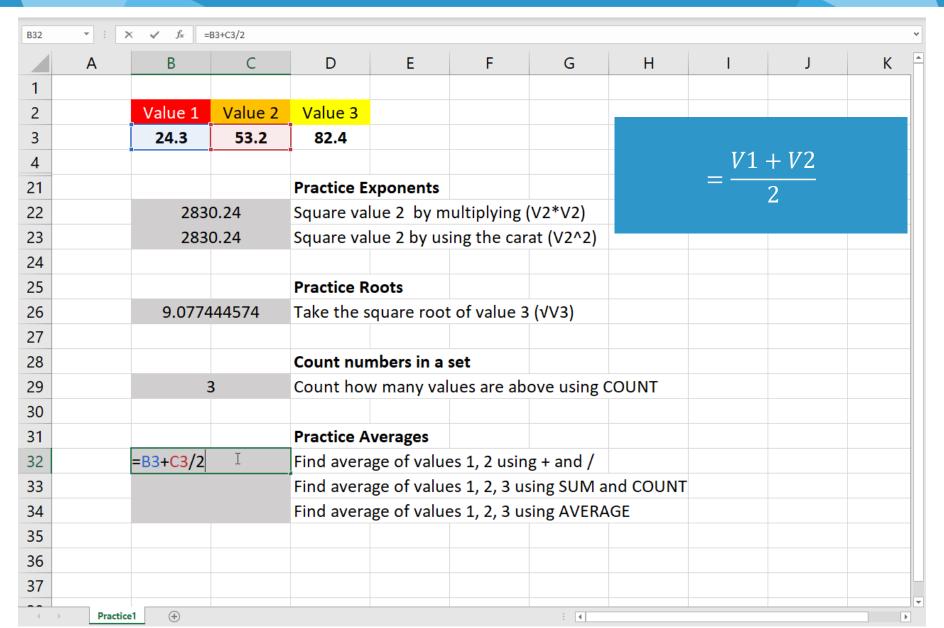




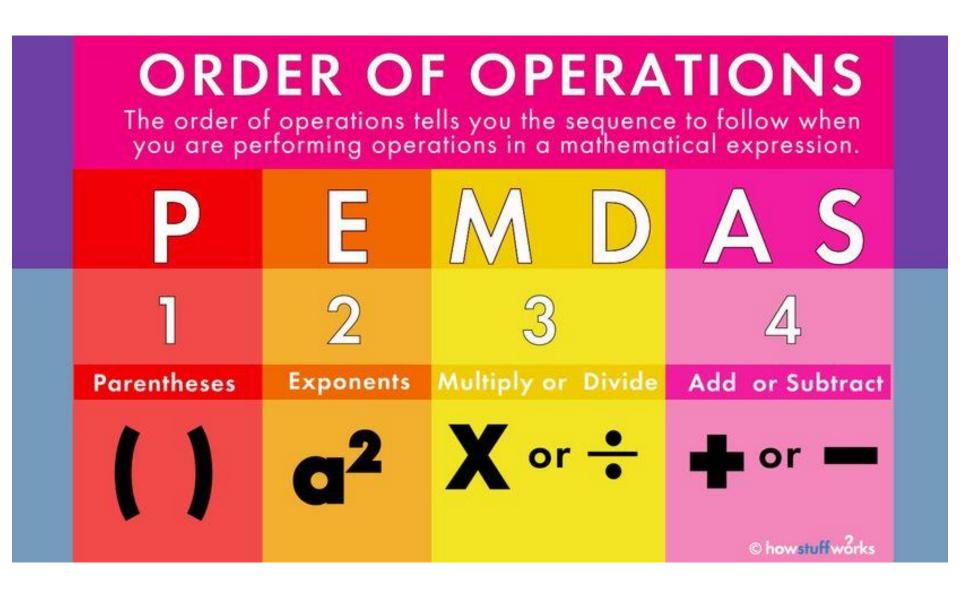












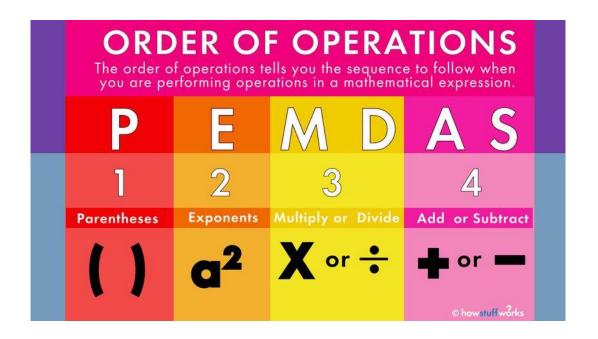
https://science.howstuffworks.com/math-concepts/PEMDAS.htm





$$= V1 + V2/2$$

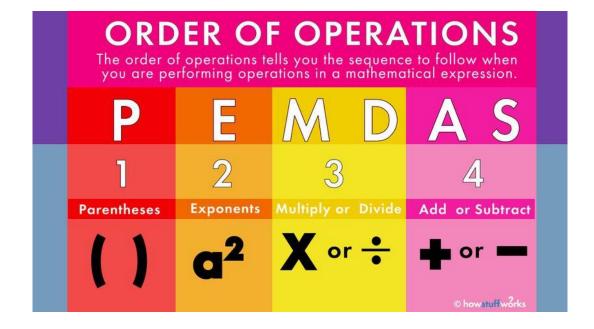
$$= V1 + \frac{V2}{2}$$





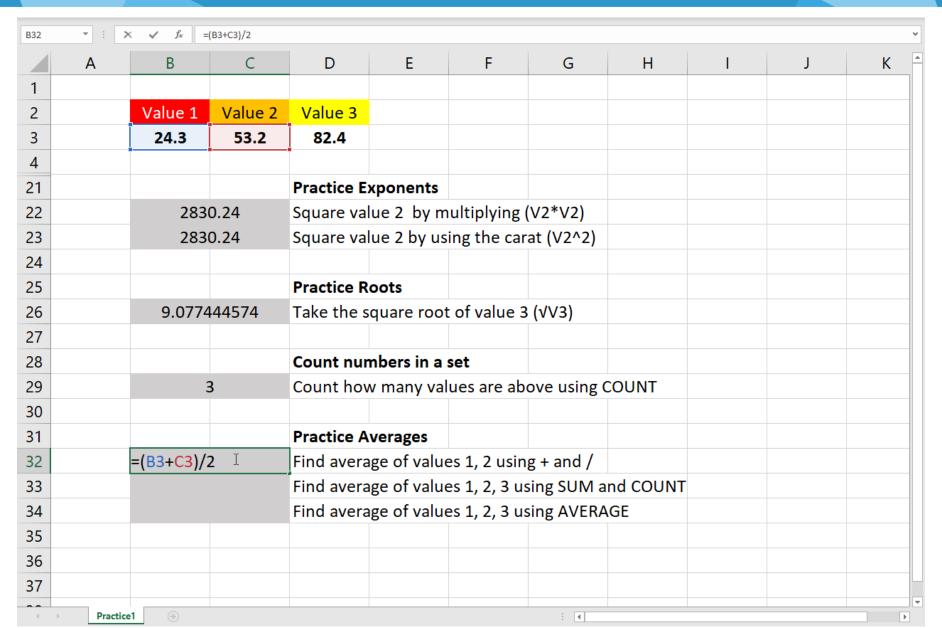
$$=\frac{V1+V2}{2}$$

$$=\frac{(V1+V2)}{2}$$

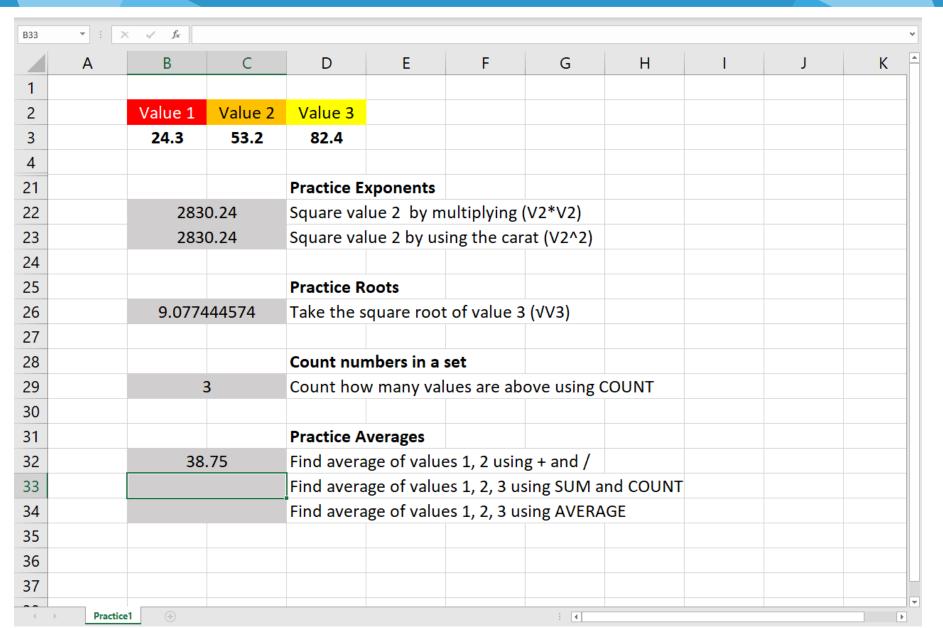


$$= (V1 + V2)/2$$

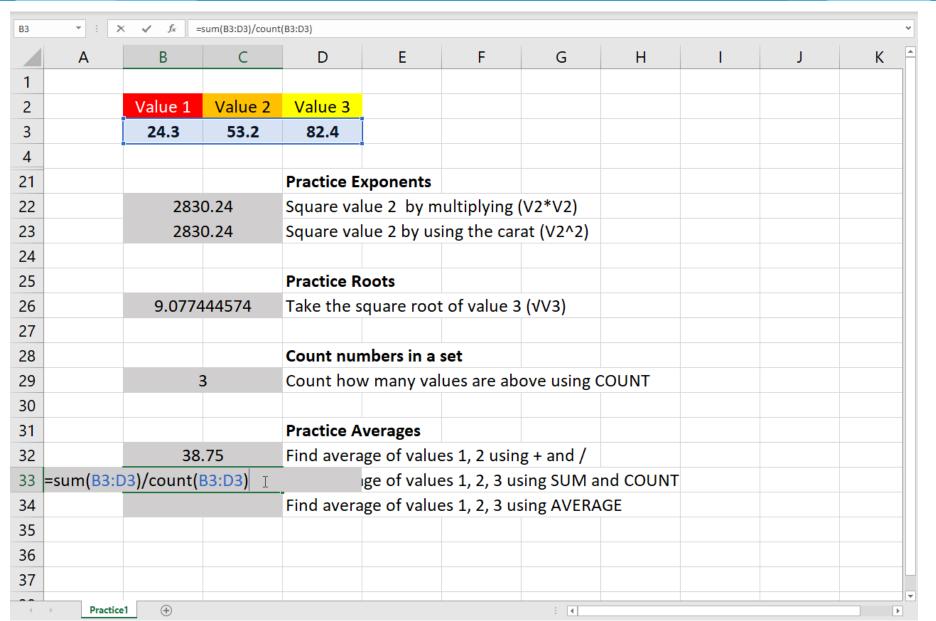




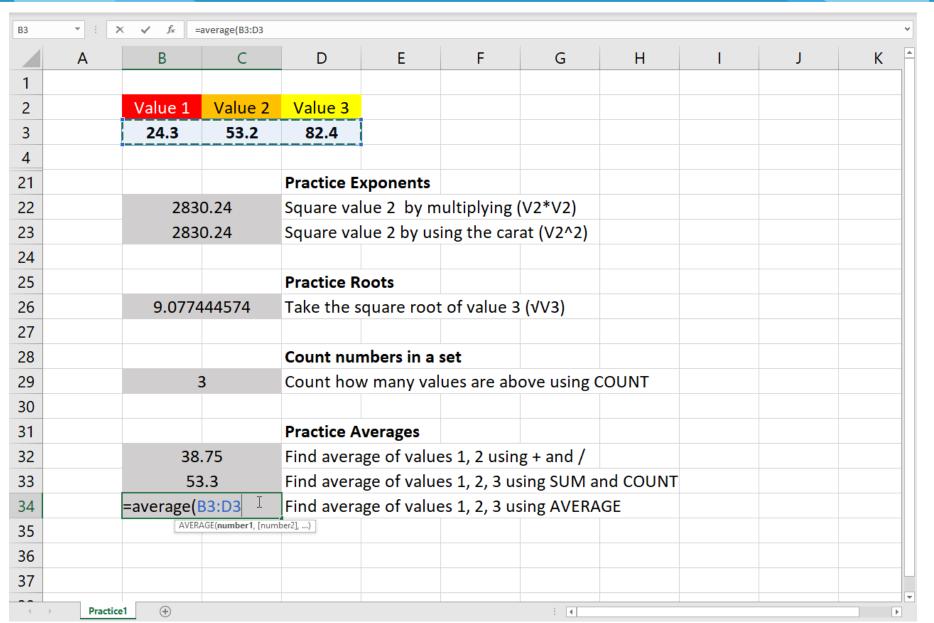














# Formula Basics

B35	▼ : >	√ f <sub>x</sub>										
	Α	В	С	D	Е	F	G	Н	1	J	K	
1												
2		Value 1	Value 2	Value 3								
3		24.3	53.2	82.4								
4												
21				Practice E	xponents							
22		2830.24		Square value 2 by multiplying (V2*V2)								
23		283	0.24	Square value 2 by using the carat (V2^2)								
24												
25				Practice R	oots							
26		9.0774	144574	Take the	quare root	t of value 3	3 (√V3)					
27												
28				Count nu	ount numbers in a set							
29		3	3	Count hov	w many val	lues are ab	ove using (	COUNT				
30												
31				Practice A	verages							
32		38	.75	Find avera	age of value	es 1, 2 usin	g + and /					
33		53	3.3	Find average of values 1, 2, 3 using SUM and COUNT								
34		53	3.3	Find avera	ge of value	es 1, 2, 3 u	sing AVERA	GE				
35												
36												
37												



# Excel Crash Reconstruction Basics

**Excel for Crash Reconstruction** 



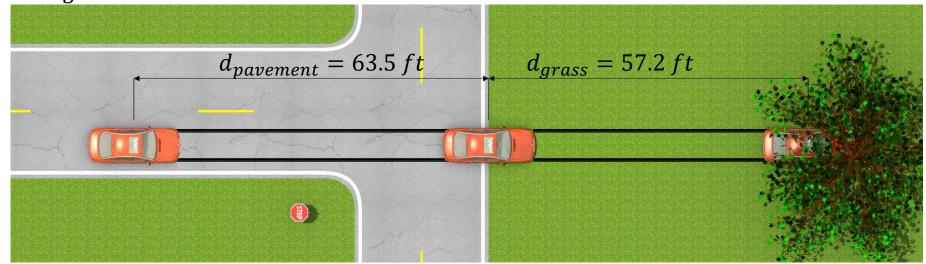


### **Scenario**

The BMW slides through a T-intersection It impacts a tree at 22 mph

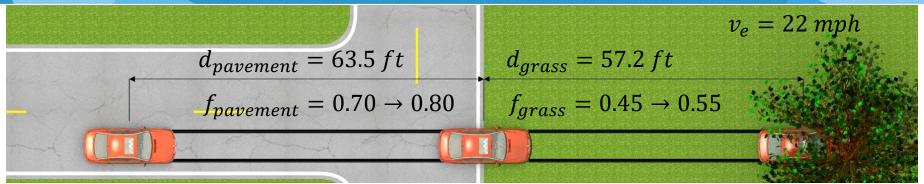
$$f_{pavement} = 0.70 \rightarrow 0.80$$

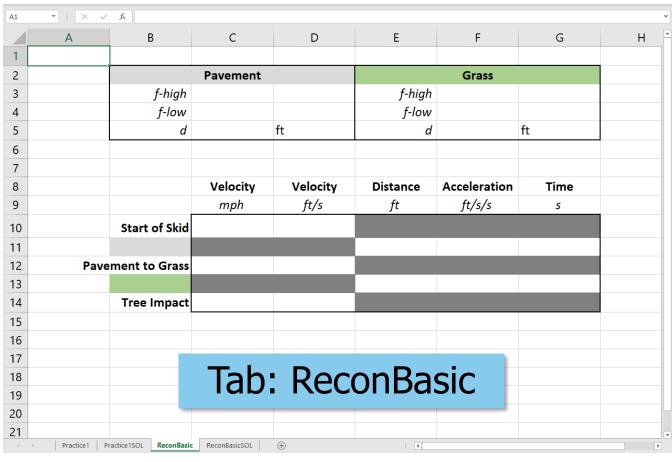
$$f_{grass} = 0.45 \rightarrow 0.55$$

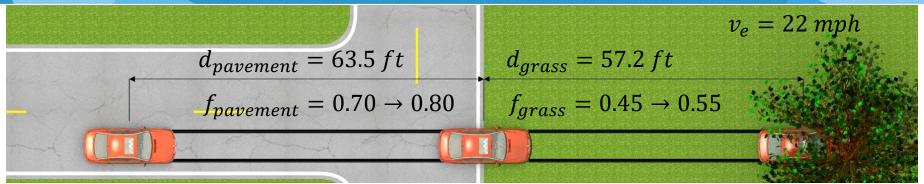


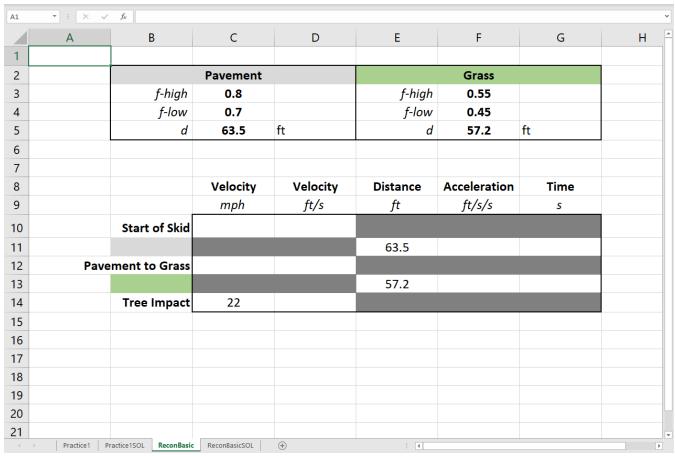
How fast was the BWM traveling when it left the pavement? How fast was the BMW traveling at the start of the skid How long was the BMW skidding?



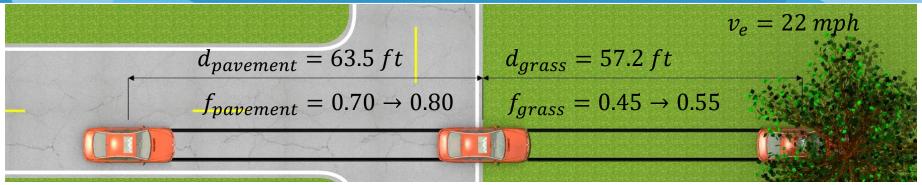


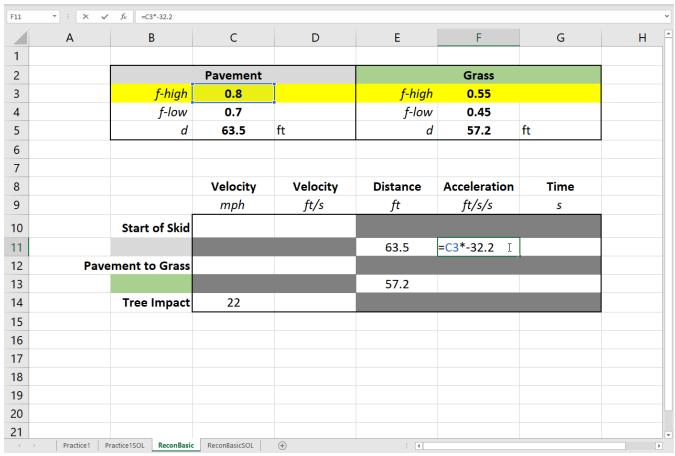




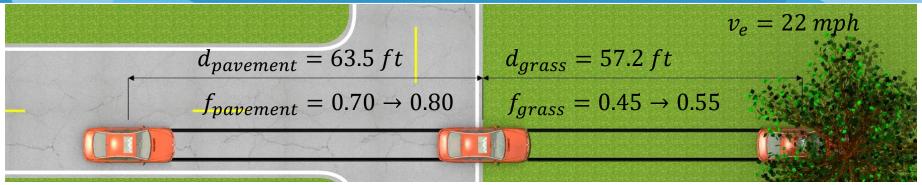


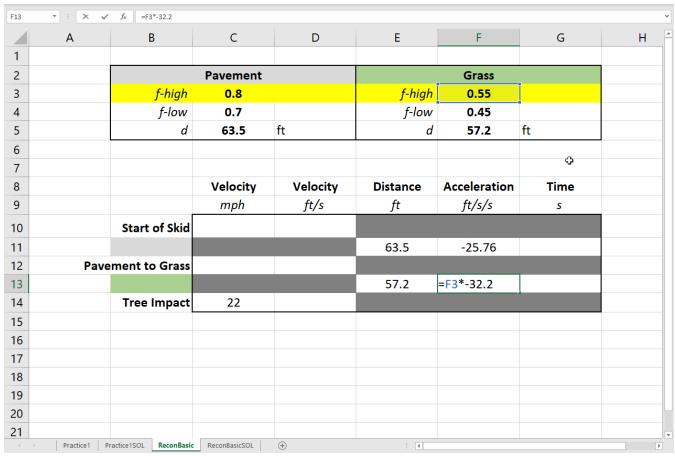




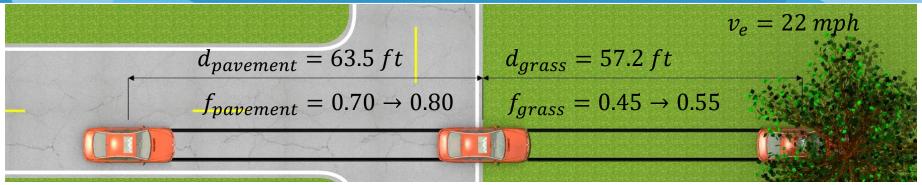


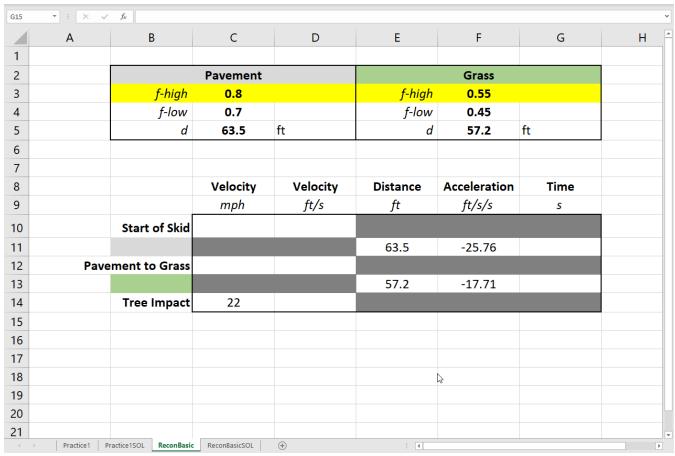




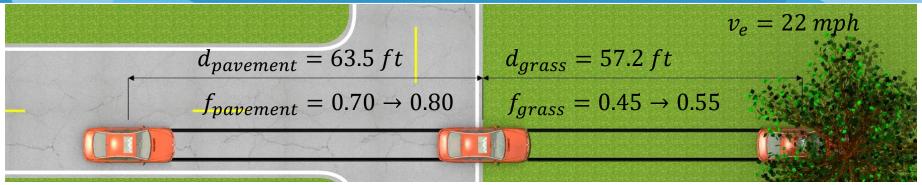


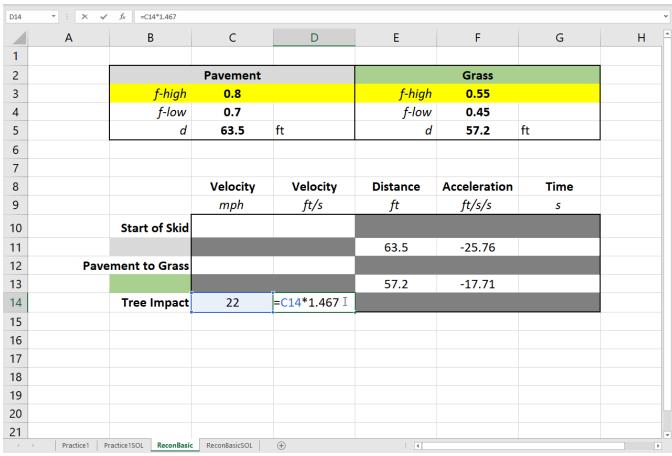


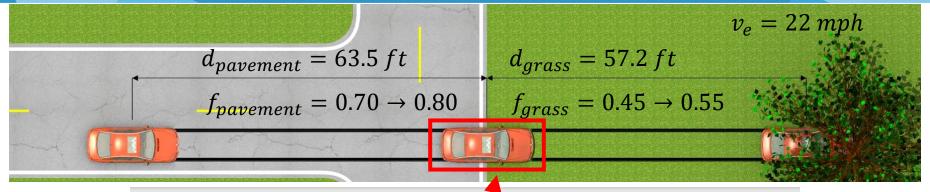


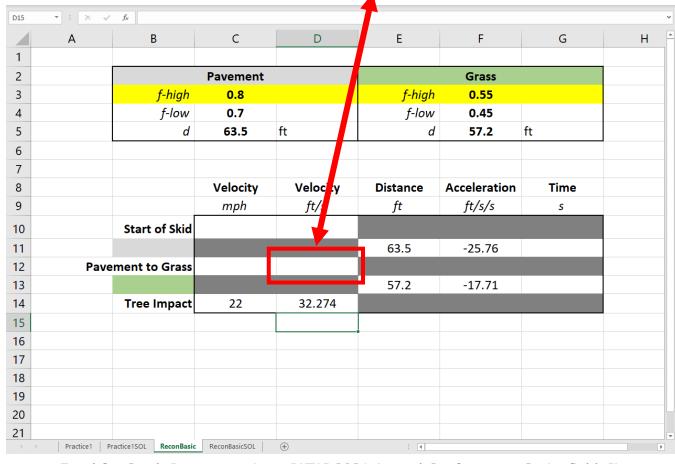














$$d_{pavement} = 63.5 \, ft$$

$$d_{grass} = 57.2 \, ft$$

$$f_{pavement} = 0.70 \rightarrow 0.80$$

$$f_{grass} = 0.45 \rightarrow 0.55$$

$$v_i = \sqrt{v_e^2 - 2ad}$$

$$v_i = \operatorname{sqrt}(v_e^2 - 2ad)$$

$$v_i = \operatorname{sqrt}((v_e^2) - (2ad))$$

$$v_i = \operatorname{sqrt}((v_e^2) - (2ad))$$



$$d_{pavement} = 63.5 \, ft$$

$$d_{grass} = 57.2 \, ft$$

$$f_{pavement} = 0.70 \rightarrow 0.80$$

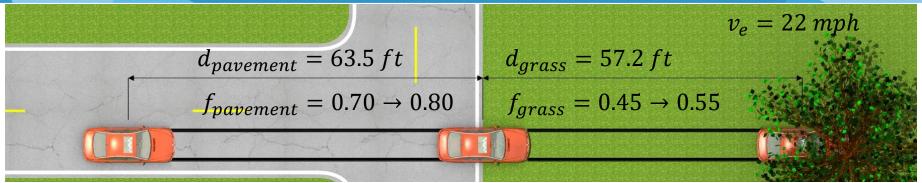
$$f_{grass} = 0.45 \rightarrow 0.55$$

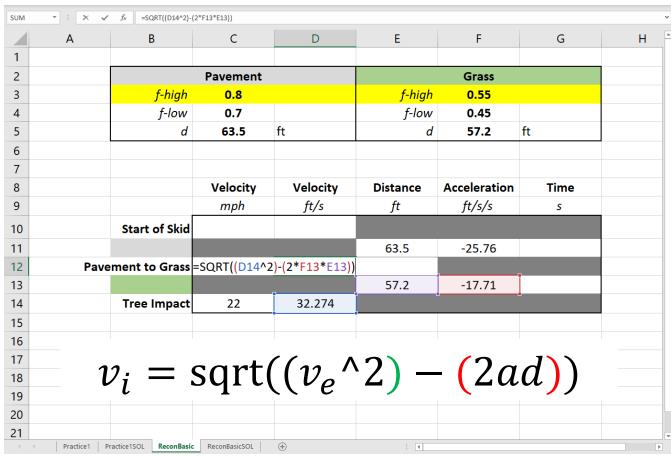


$$v_i = \operatorname{sqrt}((v_e^{}) - (2ad))$$

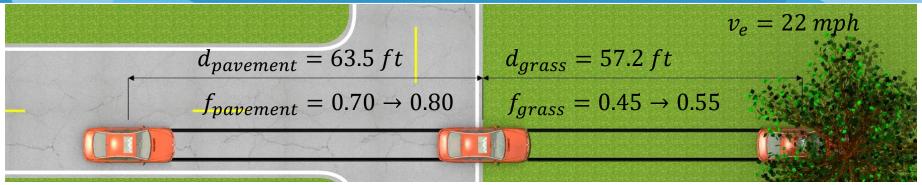












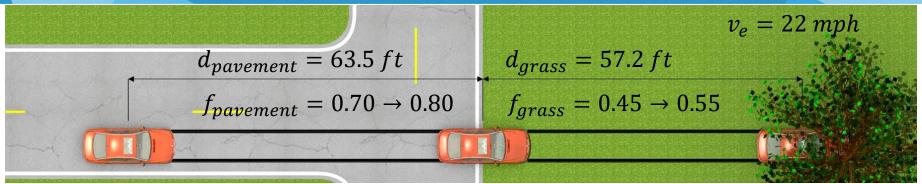
		. 1							
D12	▼ : × ✓	f <sub>sc</sub> =SQRT((D14^2)-(2	2*F13*E13))						~
	Α	В	С	D	E	F	G	Н	F
1									
2			Pavement			Grass			
3		f-high	0.8		f-high <b>0.55</b>				
4		f-low	0.7		f-low	0.45			
5		d	63.5	ft	d	57.2	ft		
6									
7									
8			Velocity	Velocity	Distance	Acceleration	Time		
9			mph	ft/s	ft	ft/s/s	5		
10		Start of Skid							
11					63.5	-25.76			1
12	Pave	ment to Grass		55.38623544					
13					57.2	-17.71			
14		Tree Impact	22	32.274					
15									
16									
17									
18									
19									
20									
21									
4	Practice1 Pr	ractice1SOL ReconBasic	ReconBasicSOL	<b>(+)</b>	: 1				Þ

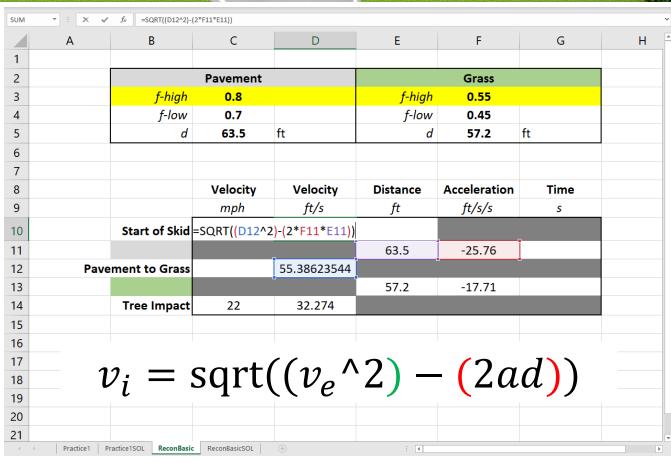
$$d_{pavement} = 63.5\,ft \qquad d_{grass} = 57.2\,ft$$
 
$$f_{pavement} = 0.70 \rightarrow 0.80 \qquad f_{grass} = 0.45 \rightarrow 0.55$$



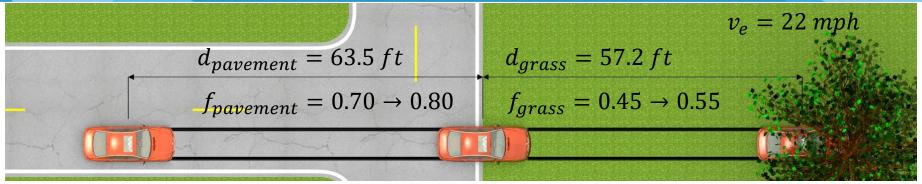


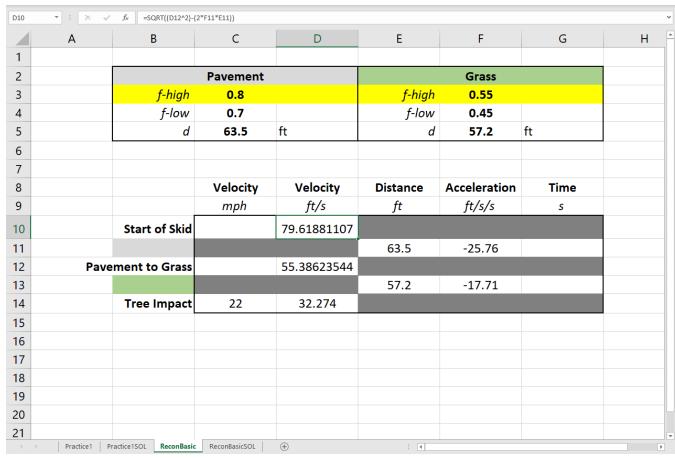




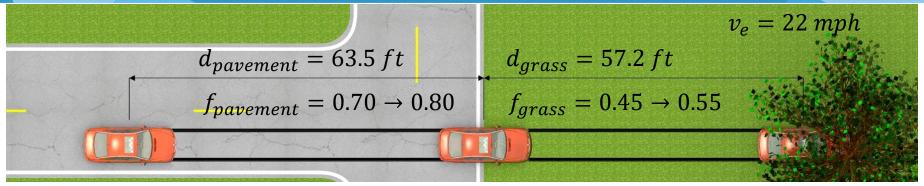


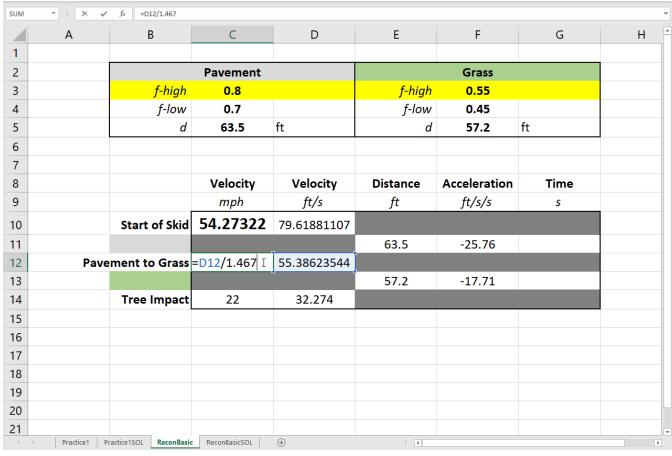


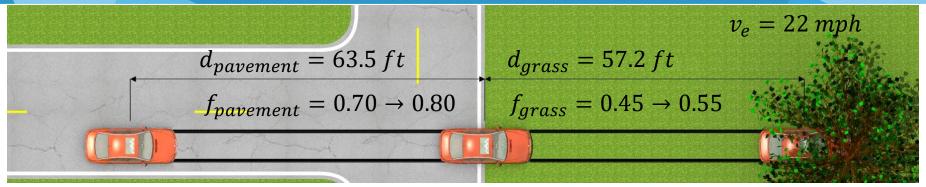


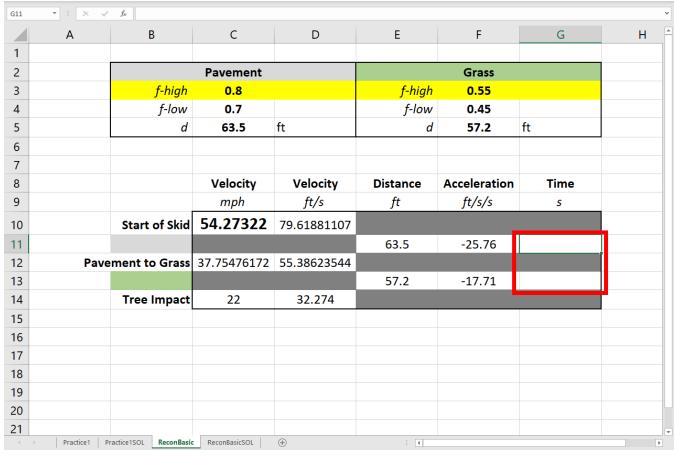




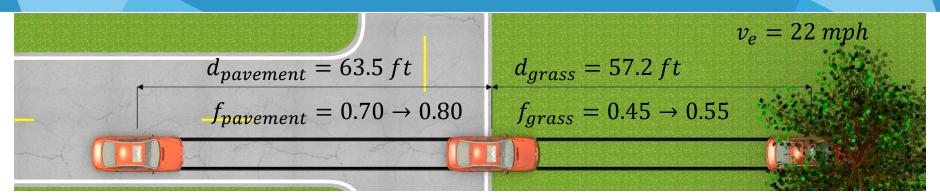












$$t = \frac{v_e - v_i}{a}$$

$$t = \frac{(v_e - v_i)}{a}$$

$$t = (v_e - v_i)/a$$

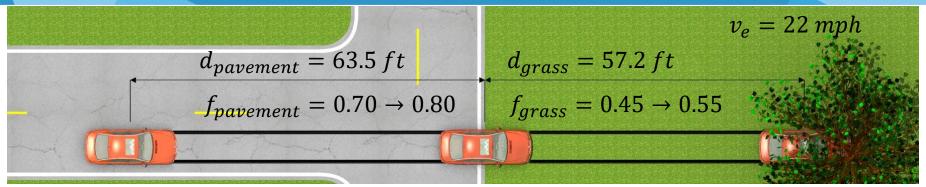


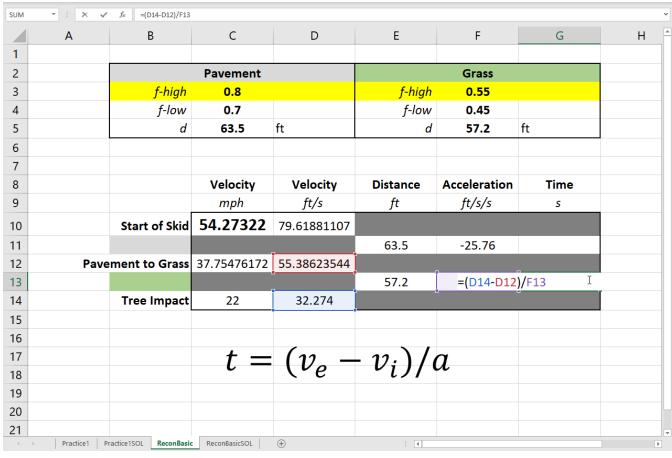
$$d_{pavement} = 63.5\,ft \qquad d_{grass} = 57.2\,ft$$
 
$$f_{pavement} = 0.70 \rightarrow 0.80 \qquad f_{grass} = 0.45 \rightarrow 0.55$$

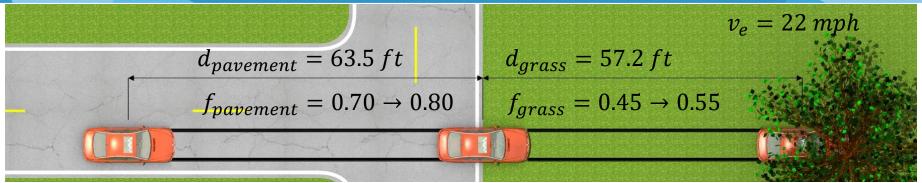


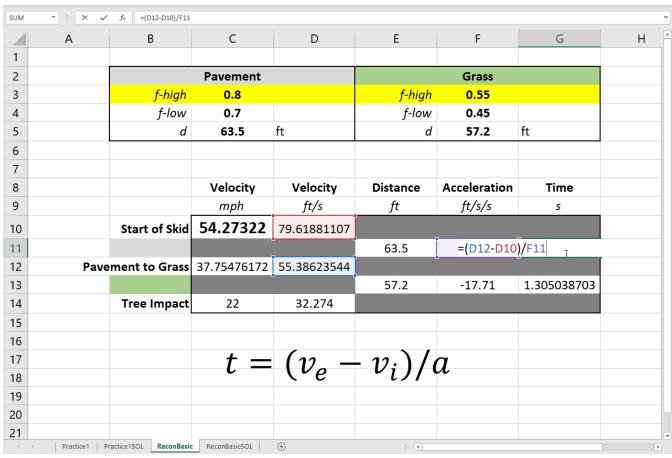




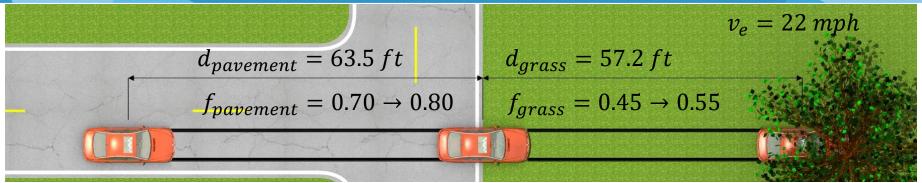


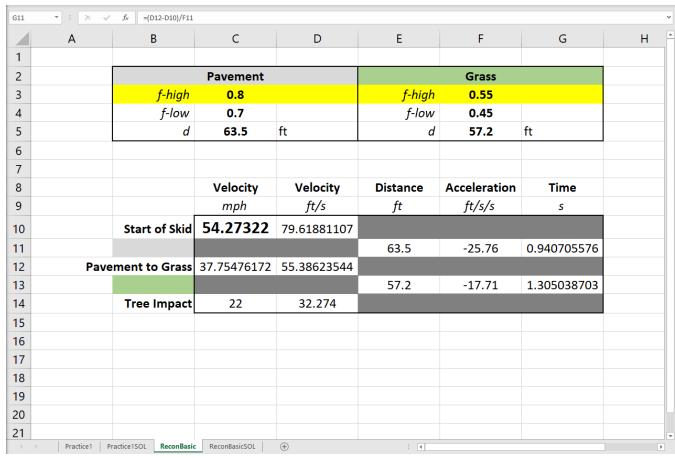














# Formatting & Conditional Formatting

**Excel for Crash Reconstruction** 





# Why bother?

Professional appearance

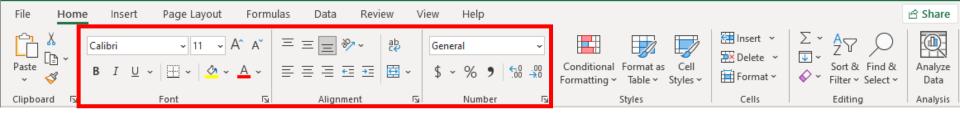
Uniform number of decimals

Simplification

Readability

	Α	В	С	D	E	F	G
1							
2			Pavement			Grass	
3		f-high	0.8		f-high	0.55	
4		f-low	0.7		f-low	0.45	
5		d	63.5	ft	d	57.2	ft
6							
7							
8			Velocity	Velocity	Distance	Acceleration	Time
9			mph	ft/s	ft	ft/\$/\$	§
18		start of skid	54? <del>27321</del> 8	79:61881187			
11					<u>83.5</u>	<u>-23:78</u>	8:348783378
	Pav <b>Pav</b>	ement to Grass	<del>37:73478172</del>	33:38823344			
13					37:2	<u>-</u> 15:51	1:383838783
14		tree impact	<u> 55</u>	<del>32:27</del> 4			





# Text size and color

Cell color

**Borders** 

Alignment

Number formatting

Cell size





**Tab: Formatting** 





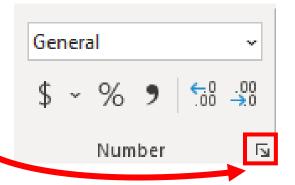






# How to display units following the calculated value:

- 1. Select cells
- 2. Select the dropdown in Number
- 3. Select "Number" category
- 4. Then select "Custom" category
- 5. Enter your units in the following format:
  - 0.0(space)(quote)(units)(quote)
    - 1-decimal: 0.0 "mph"
    - 2-decimals: 0.00 "s"
- 6. Select OK











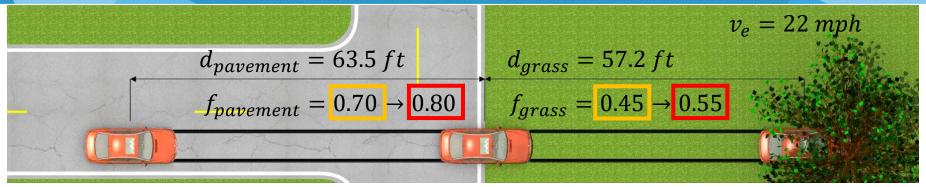
Entering custom characters: Emoji - Keep typing to Mid an emoji Windows+Period ;-) Ω Symbols Symbols 1/3 ;-) 2/3 Q 1/5 4/5 α η V١ 1/8 θ VII 3/8 Ω π Ω

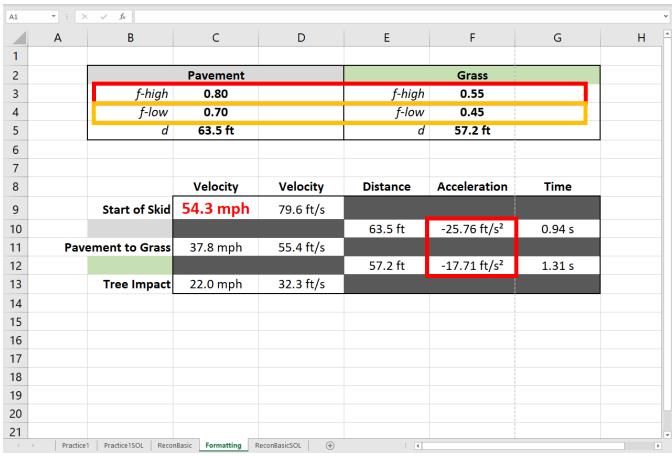












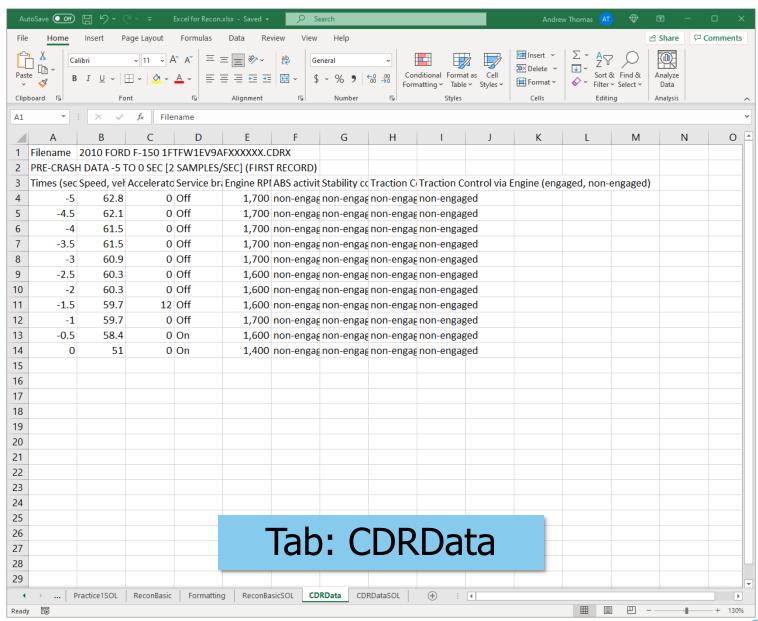




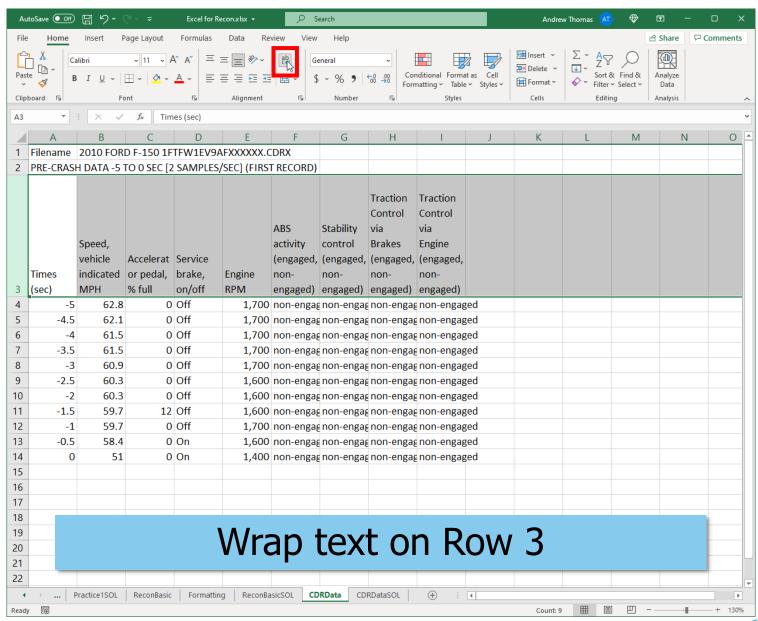




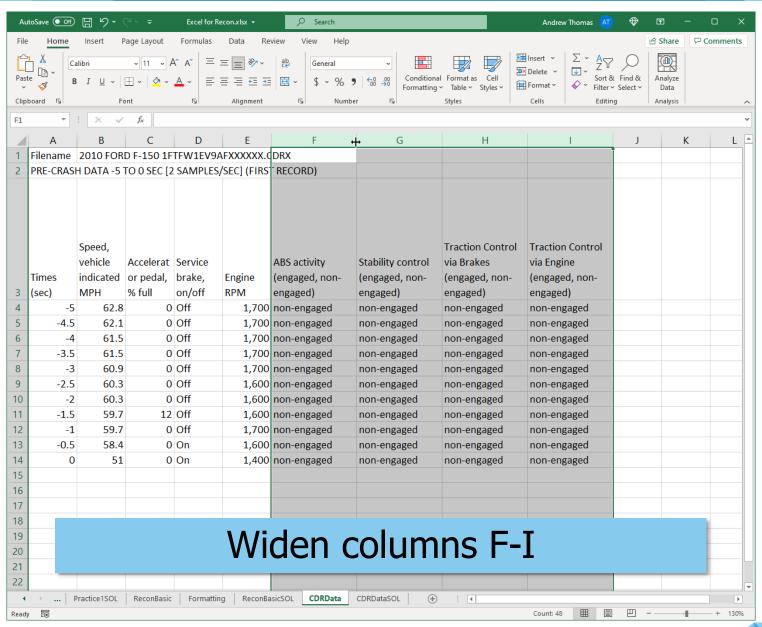
B15	▼ : ×	✓ f <sub>x</sub> Low							
	Α	В	С	D	E	F	G	Н	
1									
2			Pavement			Grass			
3		f-high	0.80		f-high	0.55	i 		
4		f-low	0.70		f-low	0.45			
5		d	63.5 ft		d	57.2 ft			
6									
7									
8		<u>High</u>	Velocity	Velocity	Distance	Acceleration	Time		
9		Start of Skid	54.3 mph	79.6 ft/s					
10					63.5 ft	-25.76 ft/s <sup>2</sup>	0.94 s		
11	Pave	ment to Grass	37.8 mph	55.4 ft/s					
12					57.2 ft	-17.71 ft/s <sup>2</sup>	1.31 s		
13		Tree Impact	22.0 mph	32.3 ft/s					
14									
15		<u>Low</u>	Velocity	Velocity	Distance	Acceleration	Time		
16		Start of Skid	50.8 mph	74.6 ft/s					
17					63.5 ft	-22.54 ft/s <sup>2</sup>	1.00 s		
18	Pave	ment to Grass	35.4 mph	52.0 ft/s					
19					57.2 ft	-14.49 ft/s <sup>2</sup>	1.36 s		
20		Tree Impact	22.0 mph	32.3 ft/s					
21	Practice1	Practice1SOL Recor	nBasic <b>Formatting</b> R	econBasicSOL +	: 1				



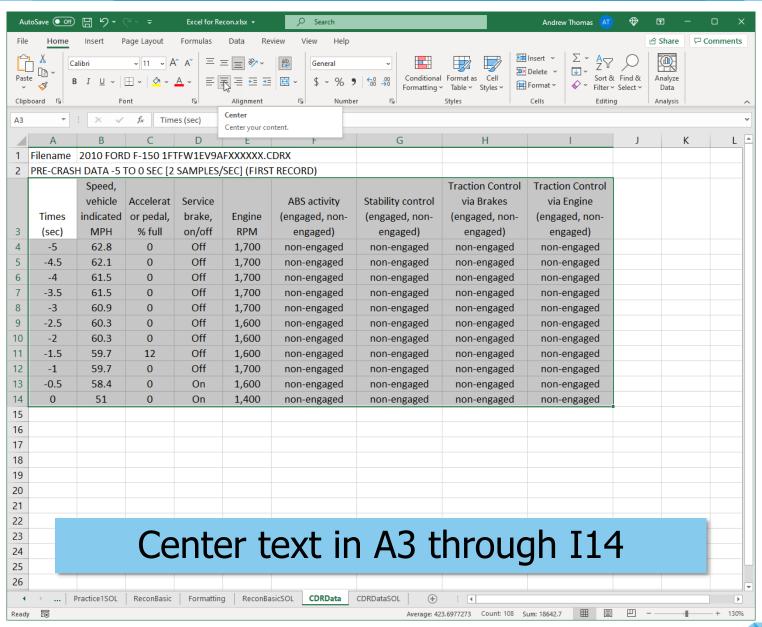














## Conditional Formatting – Number Based





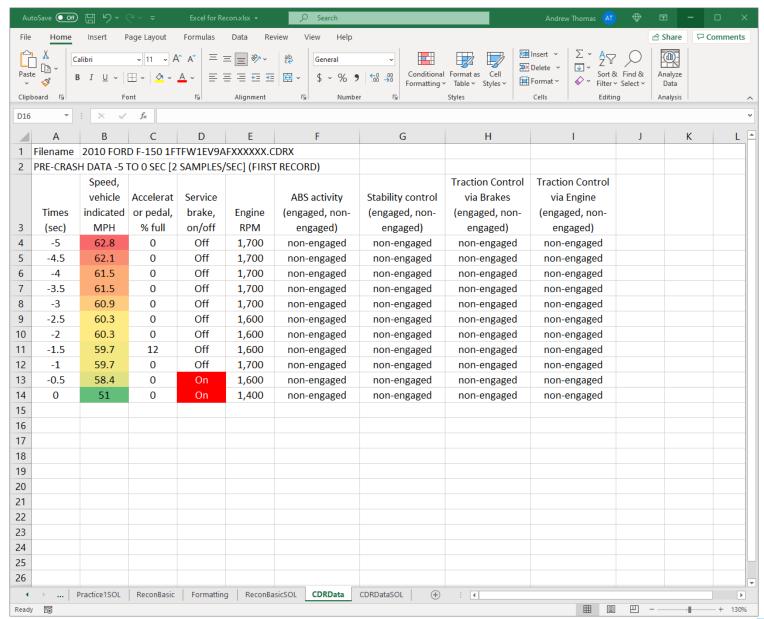


## Conditional Formatting – Text Based











0.0 fps <sup>2</sup> 1.8 fps <sup>2</sup> 0.0 fps <sup>2</sup> -3.5 fps <sup>2</sup>	0.00 -0.05 0.00
0.0 fps <sup>2</sup> 1.8 fps <sup>2</sup> 0.0 fps <sup>2</sup>	0.00
0.0 fps <sup>2</sup> 1.8 fps <sup>2</sup> 0.0 fps <sup>2</sup>	-0.05
1.8 fps <sup>2</sup>	-0.05
1.8 fps <sup>2</sup> 0.0 fps <sup>2</sup>	
0.0 fps²	
0.0 fps <sup>2</sup>	0.00
·	0.00
-3.5 fps <sup>2</sup>	
	0.11
2 F fm c <sup>2</sup>	0.11
-3.5 fps <sup>2</sup>	0.11
-3.8 fps <sup>2</sup>	0.12
-3.0 ips	0.12
-3.5 fps <sup>2</sup>	0.11
-3.8 fps <sup>2</sup>	0.12
-1.8 fps <sup>2</sup>	0.05
	0.28
	1.59
	0.50
	0.56
	2.55
-92.2 fpc2	2.55
	·

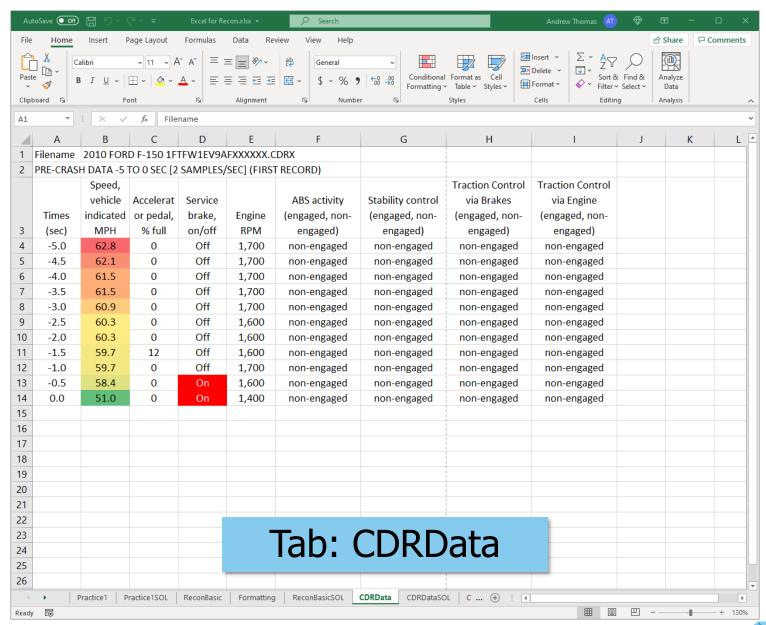


# **Printing & Copying**

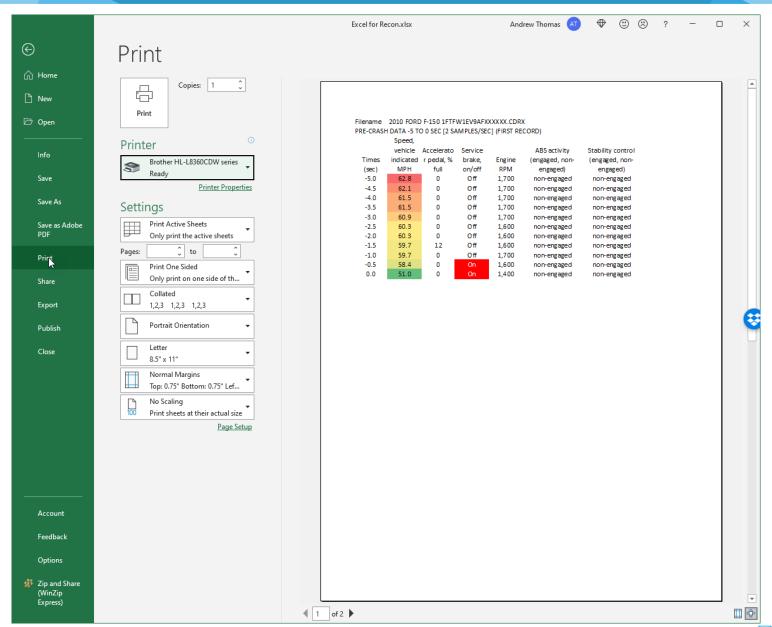
**Excel for Crash Reconstruction** 



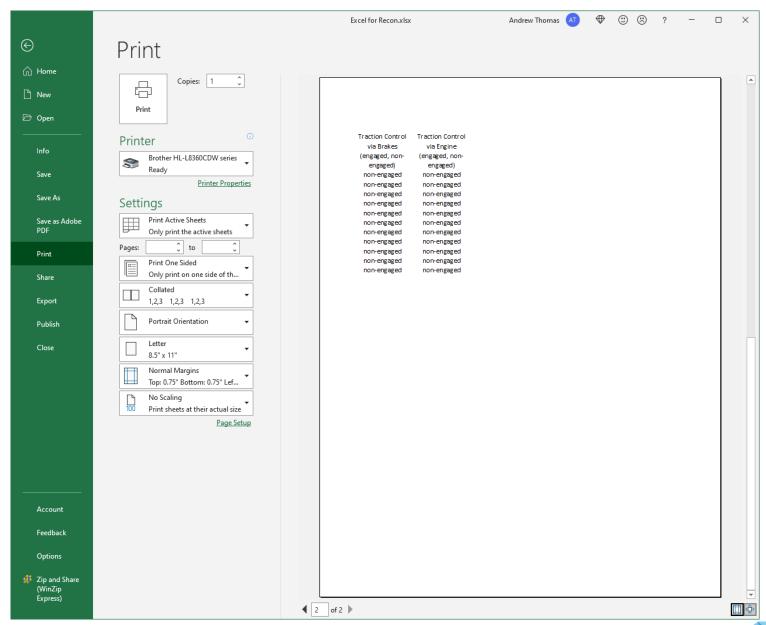




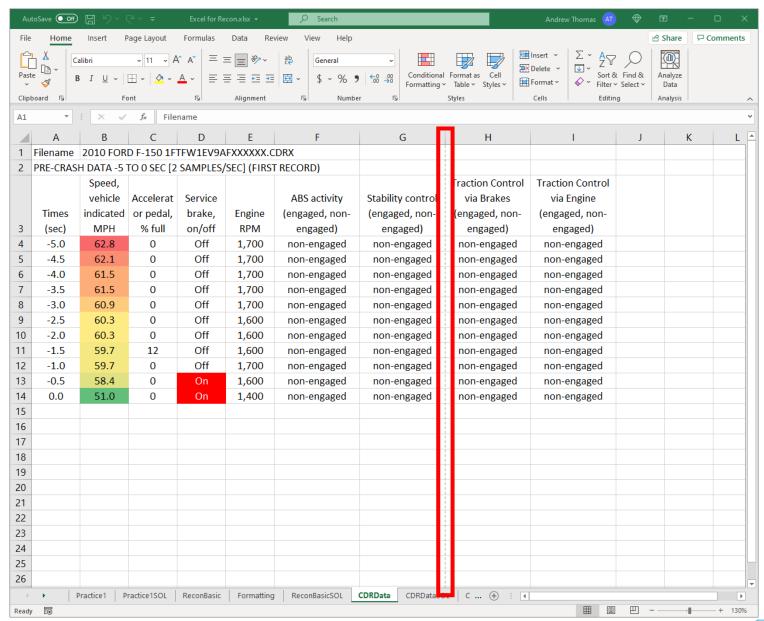




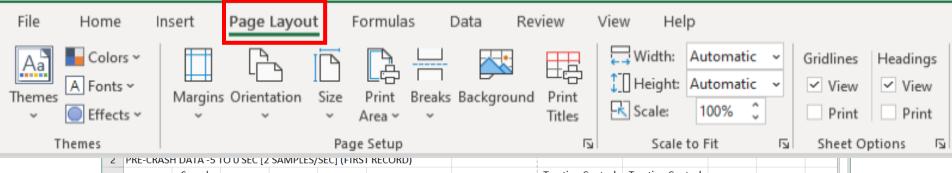




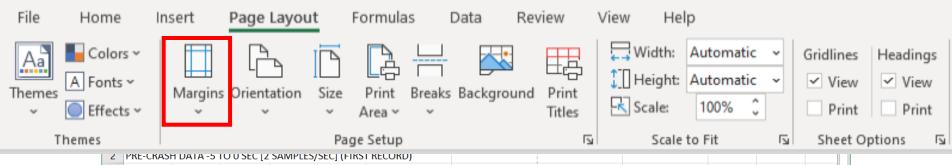




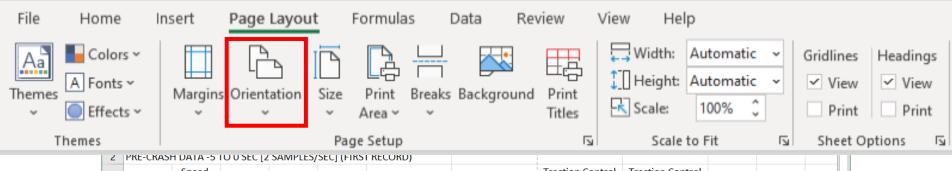




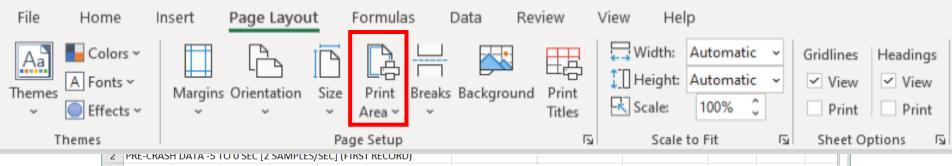
	THE CHILO		10 0 3EC [2	SAIVIPLES/	SEC] (FIKST	RECORD)					
		Speed,						Traction Control	Traction Control		
		vehicle	Accelerat	Service		ABS activity	Stability control	via Brakes	via Engine		
	Times	indicated	or pedal,	brake,	Engine	(engaged, non-	(engaged, non-	(engaged, non-	(engaged, non-		
3	(sec)	MPH	% full	on/off	RPM	engaged)	engaged)	engaged)	engaged)		
4	-5.0	62.8	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged		
5	-4.5	62.1	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged		
6	-4.0	61.5	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged		
7	-3.5	61.5	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged		
8	-3.0	60.9	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged		
9	-2.5	60.3	0	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged		
10	-2.0	60.3	0	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged		
11	-1.5	59.7	12	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged		
12	-1.0	59.7	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged		
13	-0.5	58.4	0	On	1,600	non-engaged	non-engaged	non-engaged	non-engaged		
14	0.0	51.0	0	On	1,400	non-engaged	non-engaged	non-engaged	non-engaged		
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2	PKE-CKAS	H DATA -5	IO O SEC [2	SAIVIPLES/	SEC] (FIKS)	KECUKD)					
		Speed,						Traction Control	Traction Control		
		vehicle	Accelerat	Service		ABS activity	Stability control	via Brakes	via Engine		
	Times	indicated	or pedal,	brake,	Engine	(engaged, non-	(engaged, non-	(engaged, non-	(engaged, non-		
3	(sec)	MPH	% full	on/off	RPM	engaged)	engaged)	engaged)	engaged)		
4	-5.0	62.8	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged		
5	-4.5	62.1	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged		
6	-4.0	61.5	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged		
7	-3.5	61.5	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged		
8	-3.0	60.9	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged		
9	-2.5	60.3	0	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged		
10	-2.0	60.3	0	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged		
11	-1.5	59.7	12	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged		
12	-1.0	59.7	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged		
13	-0.5	58.4	0	On	1,600	non-engaged	non-engaged	non-engaged	non-engaged		
14	0.0	51.0	0	On	1,400	non-engaged	non-engaged	non-engaged	non-engaged		
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		Speed,						Traction Control	Traction Control			
		vehicle	Accelerat	Service		ABS activity	Stability control	via Brakes	via Engine			
	Times	indicated	or pedal,	brake,	Engine	(engaged, non-	(engaged, non-	(engaged, non-	(engaged, non-			
3	(sec)	MPH	% full	on/off	RPM	engaged)	engaged)	engaged)	engaged)			
4	-5.0	62.8	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
5	-4.5	62.1	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
6	-4.0	61.5	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
7	-3.5	61.5	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
8	-3.0	60.9	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
9	-2.5	60.3	0	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
10	-2.0	60.3	0	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
11	-1.5	59.7	12	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
12	-1.0	59.7	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
13	-0.5	58.4	0	On	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
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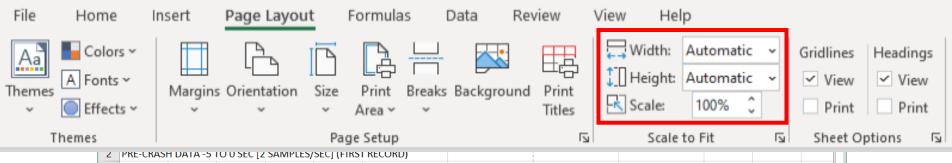
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		vehicle	Accelerat	Service		ABS activity	Stability control	via Brakes	via Engine			
	Times	indicated	or pedal,	brake,	Engine	(engaged, non-	(engaged, non-	(engaged, non-	(engaged, non-			
3	(sec)	MPH	% full	on/off	RPM	engaged)	engaged)	engaged)	engaged)			
4	-5.0	62.8	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
5	-4.5	62.1	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
6	-4.0	61.5	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
7	-3.5	61.5	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
8	-3.0	60.9	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
9	-2.5	60.3	0	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
10	-2.0	60.3	0	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
11	-1.5	59.7	12	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
12	-1.0	59.7	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
13	-0.5	58.4	0	On	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
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**Setting Print Area** 







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		Speed,						Traction Control	Traction Control			
		vehicle	Accelerat	Service		ABS activity	Stability control	via Brakes	via Engine			
	Times	indicated	or pedal,	brake,	Engine	(engaged, non-	(engaged, non-	(engaged, non-	(engaged, non-			
3	(sec)	MPH	% full	on/off	RPM	engaged)	engaged)	engaged)	engaged)			
4	-5.0	62.8	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
5	-4.5	62.1	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
6	-4.0	61.5	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
7	-3.5	61.5	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
8	-3.0	60.9	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
9	-2.5	60.3	0	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
10	-2.0	60.3	0	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
11	-1.5	59.7	12	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
12	-1.0	59.7	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
13	-0.5	58.4	0	On	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
14	0.0	51.0	0	On	1,400	non-engaged	non-engaged	non-engaged	non-engaged			
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**Adjusting Print Scale** 







**Adjusting Print Width** 

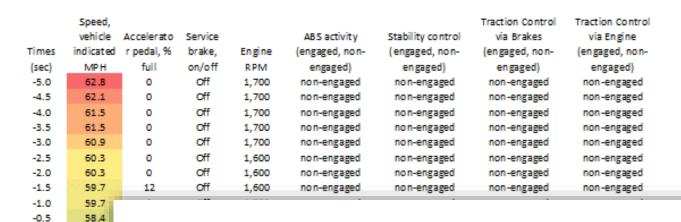






2	PKE-CKAS	H DATA -5	IO O SEC [2	SAIVIPLES/	SEC] (FIKS)	KECOKD)						
		Speed,						Traction Control	Traction Control			
		vehicle	Accelerat	Service		ABS activity	Stability control	via Brakes	via Engine			
	Times	indicated	or pedal,	brake,	Engine	(engaged, non-	(engaged, non-	(engaged, non-	(engaged, non-			
3	(sec)	MPH	% full	on/off	RPM	engaged)	engaged)	engaged)	engaged)			
4	-5.0	62.8	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
5	-4.5	62.1	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
6	-4.0	61.5	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
7	-3.5	61.5	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
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10	-2.0	60.3	0	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
11	-1.5	59.7	12	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
12	-1.0	59.7	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged			
13	-0.5	58.4	0	On	1,600	non-engaged	non-engaged	non-engaged	non-engaged			
14	0.0	51.0	0	On	1,400	non-engaged	non-engaged	non-engaged	non-engaged			
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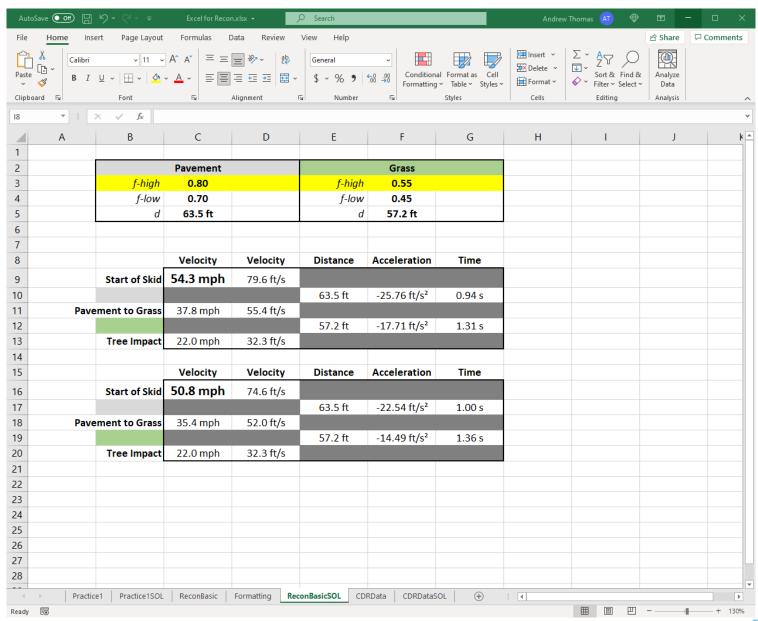
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		Speed,						Traction Control	Traction Control
		vehicle	Accelerat	Service		ABS activity	Stability control	via Brakes	via Engine
	Times	indicated	or pedal,	brake,	Engine	(engaged, non-	(en gaged, non-	(engaged, non-	(engaged, non-
3	(sec)	MPH	% full	on/off	RPM	engaged)	engaged)	engaged)	engaged)
4	-5.0	62.8	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged
5	-4.5	62.1	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged
6	-4.0	61.5	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged
7	-3.5	61.5	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged
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9	-2.5	60.3	0	Off	1,600	non-engaged	non-engaged	non-engaged	non-engaged
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12	-1.0	59.7	0	Off	1,700	non-engaged	non-engaged	non-engaged	non-engaged
13	-0.5	58.4	0	On	1,600	non-engaged	non-engaged	non-engaged	non-engaged
14	0.0	51.0	0	On	1,400	non-engaged	non-engaged	non-engaged	non-engaged

#### Copying





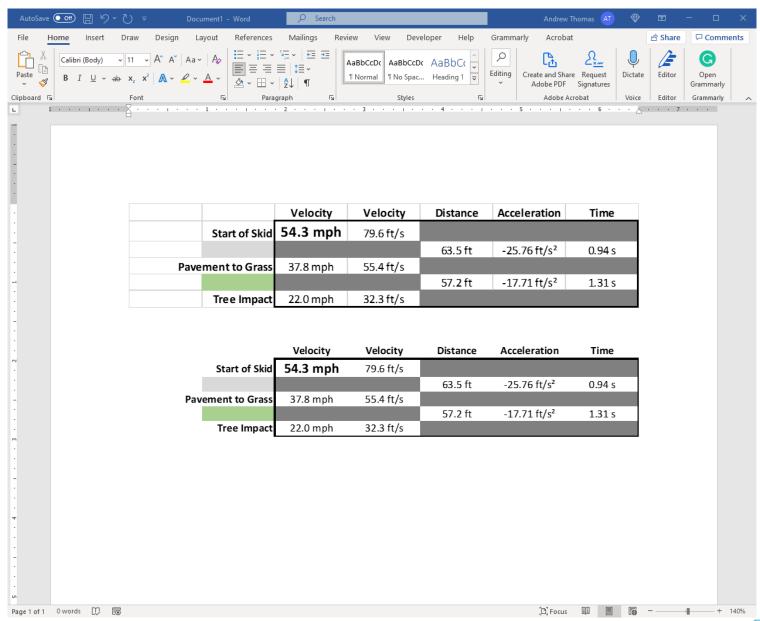
## Copying







## Copying





**Excel for Crash Reconstruction** 





$$\Delta v_{TOT} = \sqrt{\Delta v_x^2 + \Delta v_y^2}$$

$$a = \frac{v_e - v_i}{t}$$

$$v_1 = \frac{v_1' w_1 + v_2' w_2 - v_2 w_2}{w_1}$$

$$v = \sqrt{\frac{gr(\mu + G)}{1 - \mu G}}$$

$$t = \frac{(v_e - v_i)}{a}$$

$$v_e = \sqrt{v_i^2 + 2ad}$$

$$a = \frac{2d - 2v_i t}{t^2}$$

$$v_e = \frac{(v_e - v_i)}{a}$$

$$v_e = \sqrt{v_i^2 + 2ad}$$

$$a = \frac{2d - 2v_i t}{t^2}$$

$$v_c = \sqrt{\frac{2E_d g(w_f + w_c v_c') \cos \theta' - w_c v_c}{v_c}}$$

$$v_c = \sqrt{\frac{2E_d g(w_f + w_c v_c') \cos \theta'}{v_c}}$$

 $a = \frac{2d - 2v_i t}{t^2}$   $v_c = \sqrt{\frac{2E_d g(w_f + w_r)}{w_f w_r}}$ 

 $a = \frac{v_e^2 - v_i^2}{2d} \ v_1 = \frac{w_1 v_1' \cos \theta_1' + w_2 v_2' \cos \theta_2' - w_2 v_2 \cos \theta_2}{w_1 \cos \theta_1}$  $v_{\rho} = v_i + at$ 

 $l_{r} = \frac{w_{f}l}{w} \qquad v_{i} = v_{e}$   $d = \frac{v_{e}^{2} - v_{i}^{2}}{2a} \qquad l_{z} = \left(\frac{l\sqrt{l^{2} - h^{2}}(w_{h} - w_{f})}{hw}\right) + r$   $v_{i} = \sqrt{v_{e}^{2} - 2ad} \qquad v = d\sqrt{\frac{g}{2(dG - h)}} \qquad v_{i} = \frac{d}{t} - \frac{at}{2}$   $v_{r} = v' + \left(\frac{w_{f}v_{c}}{w_{f} + w_{r}}\right)$   $d = v_{i}t + \frac{1}{2}at^{2}$   $d = \frac{t(v_{i} + v_{e})}{2}$ 

 $t = \frac{-v_i + \sqrt{v_i^2 - 2a(-d)}}{a}$   $f_{eff} = \mu \sqrt{\sin(\beta)^2 + \left(\frac{f_{long}}{\mu}\right)^2 \cos(\beta)^2}$ Excel for Crash Reconstruction - IATAI 2021 Annual Conference - Springfield, IL

$$E = W \left[ G + \frac{A}{2} (C_1 + C_2) + \frac{B}{6} (C_1^2 + C_2^2 + C_1 C_2) \right] (1 + (tan\theta)^2)$$

$$v_2 = \frac{w_1 v_1' \sin \theta_1' + w_2 v_2' \sin \theta_2'}{w_2 \sin \theta_2}$$

$$v_1 = \frac{w_1 v_1' \cos \theta_1' + w_2 v_2' \cos \theta_2' - w_2 v_2 \cos \theta_2}{w_1 \cos \theta_1}$$



$$\begin{split} & E = W \left[ G + \frac{A}{2} (C_1 + C_2) + \frac{B}{6} (C_1^2 + C_2^2 + C_1 C_2) \right] \left( 1 + (\tan \theta)^2 \right) \\ & E = W (G + \frac{A}{2} (C_1 + C_2) + \frac{B}{6} (C_1^2 + C_2^2 + C_1 C_2)) (1 + (\tan \theta)^2) \\ & E = W (G + (\frac{A}{2}) (C_1 + C_2) + (\frac{B}{6}) (C_1^2 + C_2^2 + C_1 C_2)) (1 + (\tan \theta)^2) \\ & E = W (G + (A/2) (C_1 + C_2) + (B/6) (C_1^2 + C_2^2 + C_1 C_2)) (1 + (\tan \theta)^2) \\ & E = W * (G + ((A/2) * (C_1 + C_2)) + ((B/6) * (C_1^2 + C_2^2 + (C_1 * C_2)))) * (1 + (\tan \theta)^2) \\ & E = W * (G + ((A/2) * (C_1 + C_2)) + ((B/6) * ((C_1^2 + C_2^2 + (C_1 * C_2)))) * (1 + ((\tan \theta)^2)) \end{split}$$

 $\theta$  is measured in degrees

Excel only calculates trig functions in radians

$$tan(\theta)$$

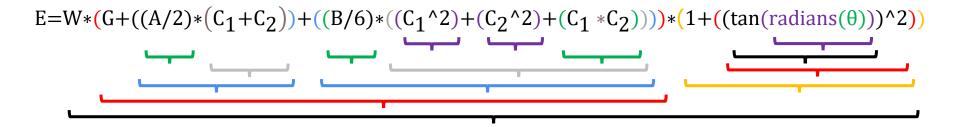
 $tan(radians(\theta))$ 

$$E=W*(G+((A/2)*(C_1+C_2))+((B/6)*((C_1^2)+(C_2^2)+(C_1*C_2))))*(1+((tan(radians(\theta)))^2))$$

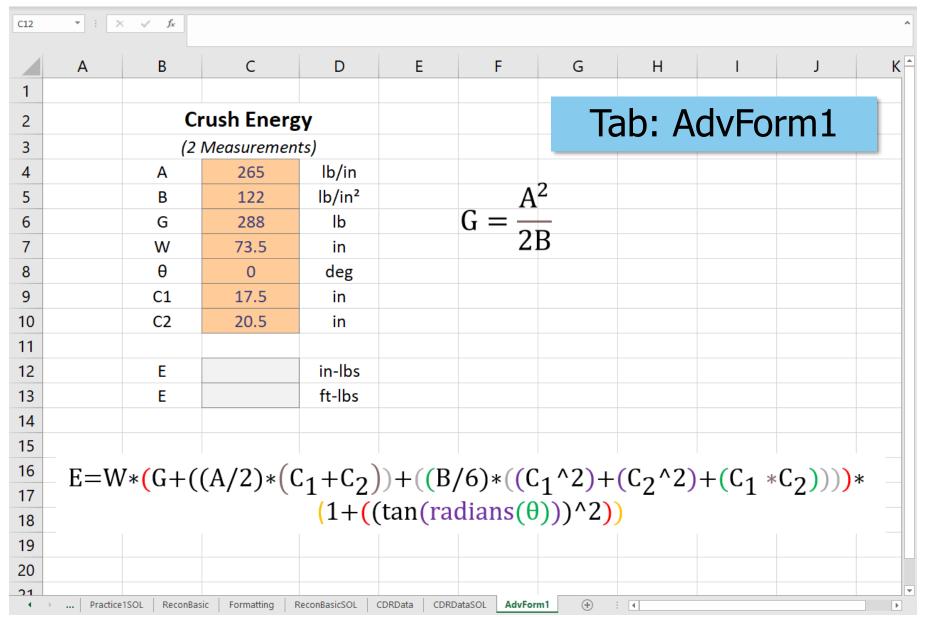


$$\text{E=W}\left[\text{G} + \frac{\text{A}}{2}(\text{C}_1 + \text{C}_2) + \frac{\text{B}}{6}\left(\text{C}_1^2 + \text{C}_2^2 + \text{C}_1\text{C}_2\right)\right] \left(1 + (\tan\theta)^2\right)$$

$$G = \frac{A^2}{2B}$$





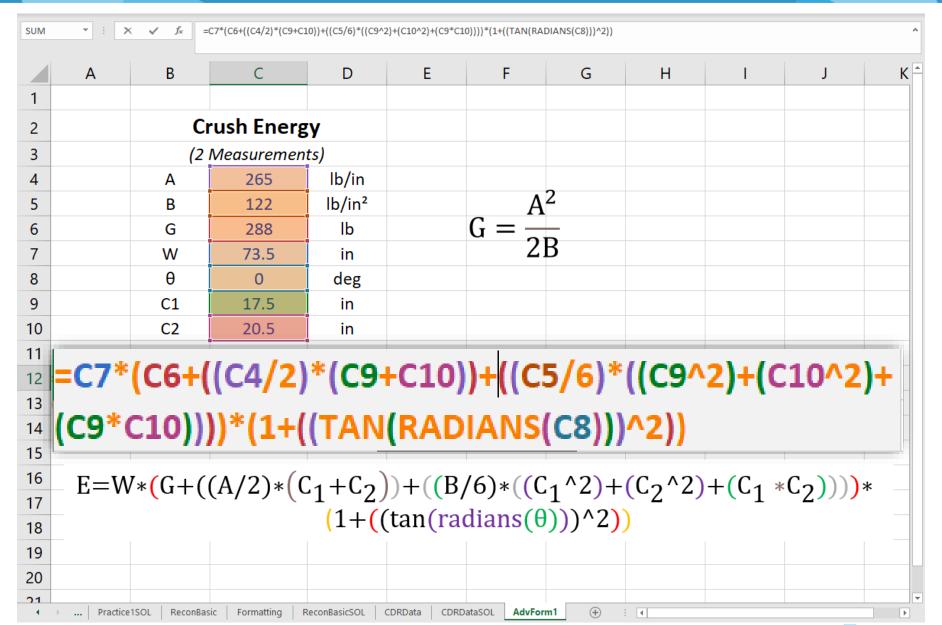




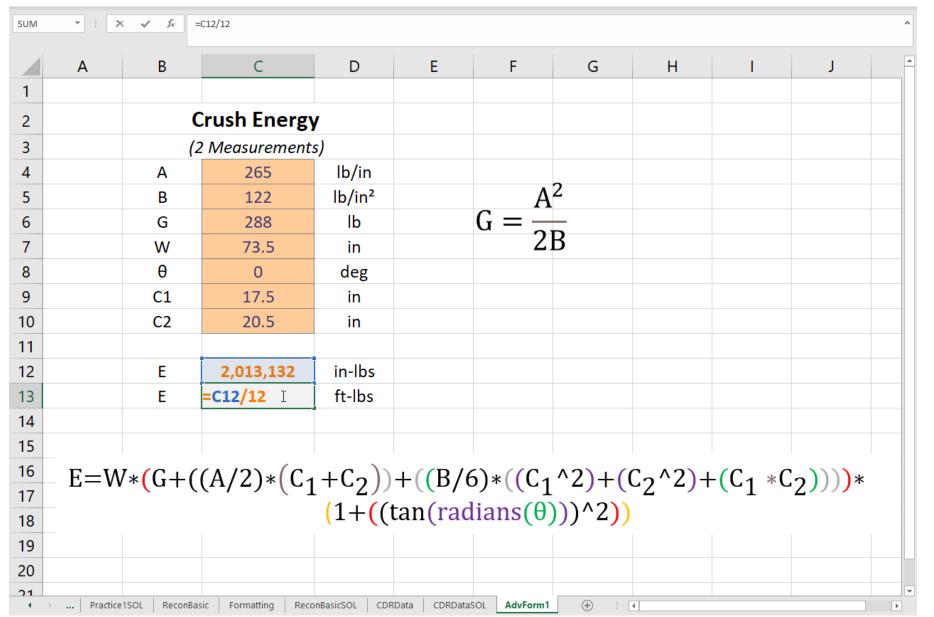




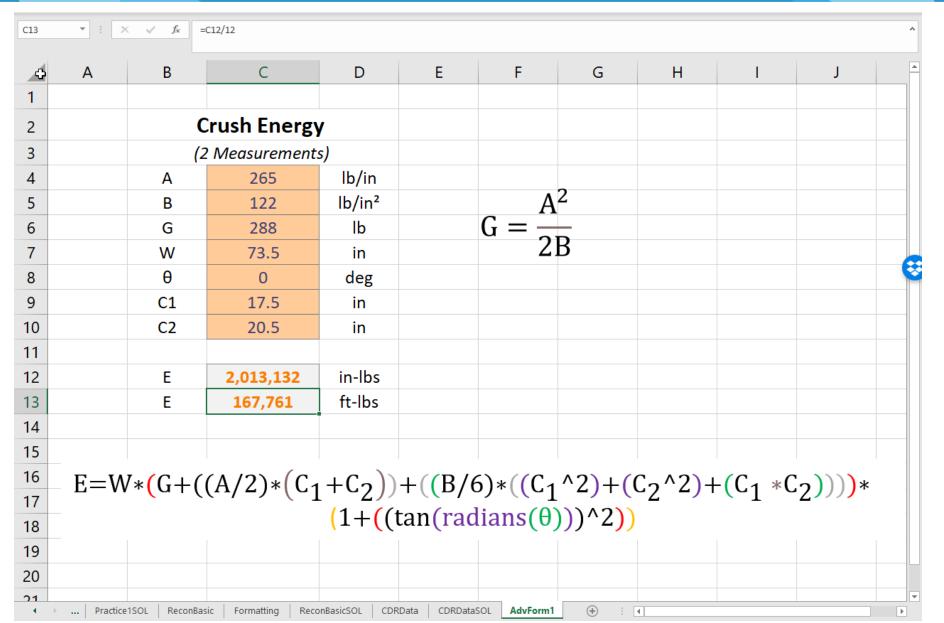














$$v_{2} = \frac{w_{1}v_{1}' \sin \theta_{1}' + w_{2}v_{2}' \sin \theta_{2}'}{w_{2} \sin \theta_{2}}$$

$$v_{2} = \frac{(w_{1}v_{1}' \sin \theta_{1}' + w_{2}v_{2}' \sin \theta_{2}')}{(w_{2} \sin \theta_{2})}$$

$$v_{2} = (w_{1}v_{1}' \sin \theta_{1}' + w_{2}v_{2}' \sin \theta_{2}') / (w_{2} \sin \theta_{2})$$

$$v_{2} = ((w_{1}v_{1}' \sin \theta_{1}') + (w_{2}v_{2}' \sin \theta_{2}')) / (w_{2} \sin \theta_{2})$$

$$v_{2} = ((w_{1} * v_{1}' * \sin \theta_{1}') + (w_{2} * v_{2}' * \sin \theta_{2}')) / (w_{2} * \sin \theta_{2})$$

$$v_{2} = ((w_{1} * v_{1}' * (\sin \theta_{1}')) + (w_{2} * v_{2}' * (\sin \theta_{2}'))) / (w_{2} * (\sin \theta_{2}))$$

$$(radians(\theta_{1}'))$$

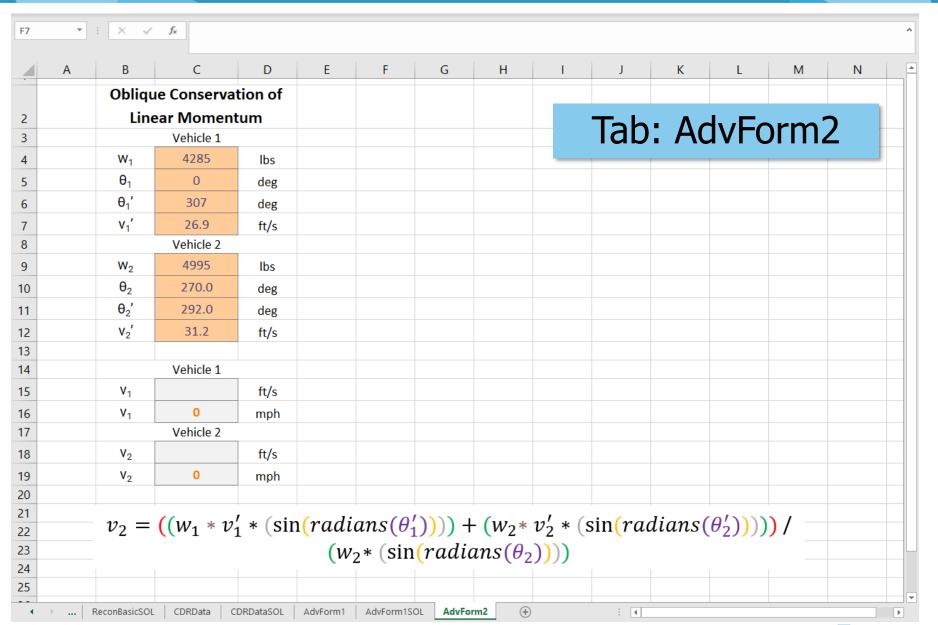
$$v_{2} = ((w_{1} * v_{1}' * (\sin(radians(\theta_{1}')))) + (w_{2} * v_{2}' * (\sin(radians(\theta_{2}'))))) / (w_{2} * (\sin(radians(\theta_{2}'))))$$



$$v_2 = \frac{w_1 v_1' \sin \theta_1' + w_2 v_2' \sin \theta_2'}{w_2 \sin \theta_2}$$

$$v_{2} = ((w_{1} * v'_{1} * (\sin(radians(\theta'_{1})))) + (w_{2} * v'_{2} * (\sin(radians(\theta'_{2}))))) / (w_{2} * (\sin(radians(\theta_{2}))))$$



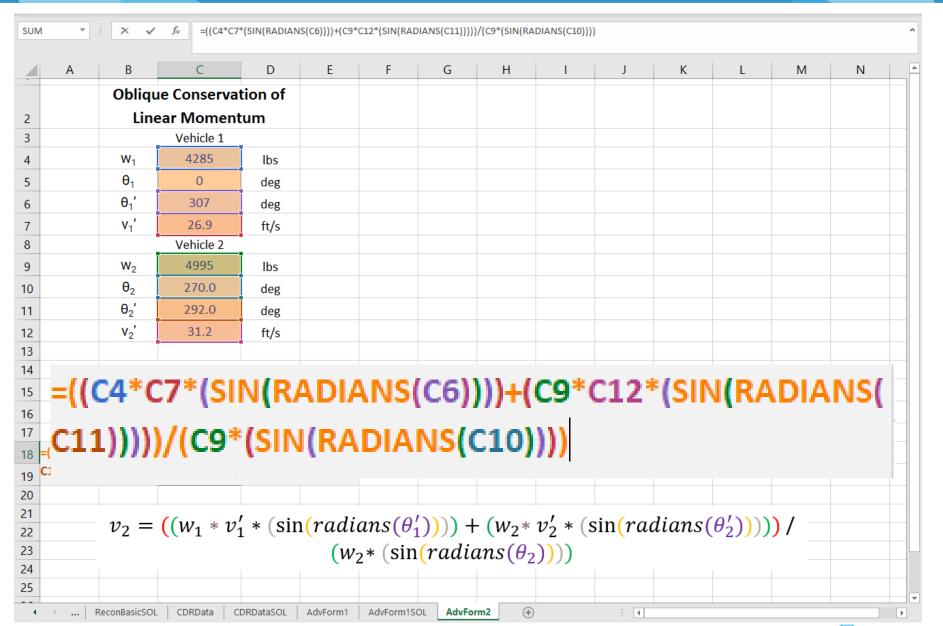




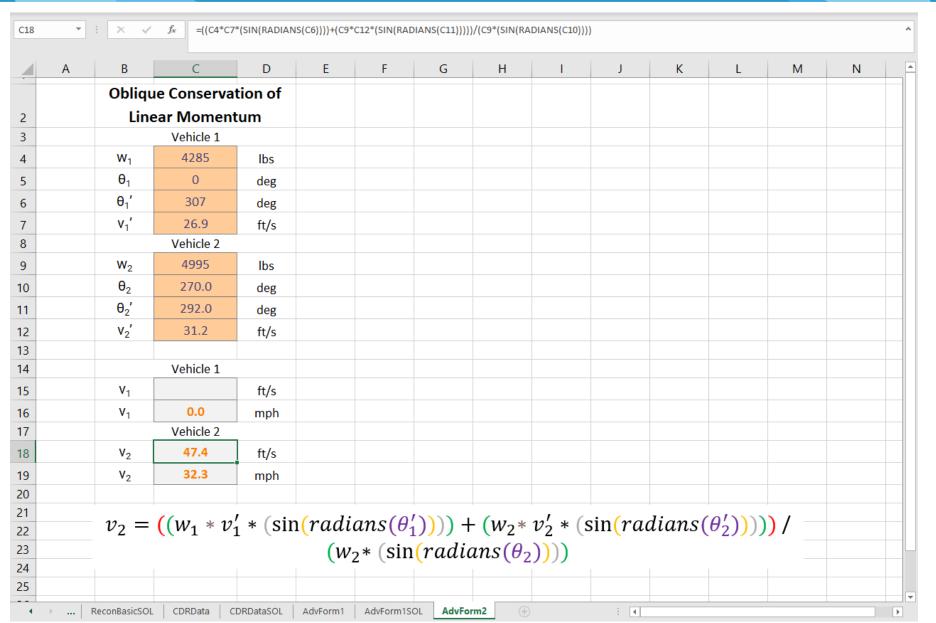




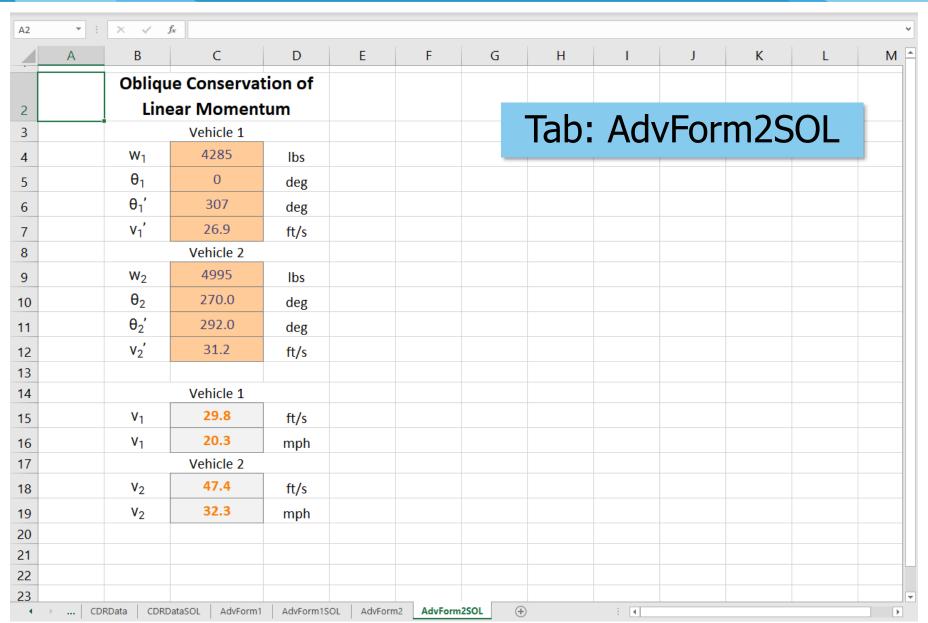














#### Disclaimer

# **Check your calculations!**

Use training material Hand crunch your numbers

## Be cautious of recon software

# **Keep learning**

Recon classes

Recon Excel classes

Community College

**Internet Videos** 







# **Andrew W. Thomas**

andrew@collisionanalyticsllc.com www.collisionanalyticsllc.com (815) 260-3721

